

APPROXIMATE ENDPOINT SOLUTIONS FOR A CLASS OF FRACTIONAL q -DIFFERENTIAL INCLUSIONS BY COMPUTATIONAL RESULTS

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Abstract

By using the notion of endpoints for set-valued functions and some classical fixed point techniques, we investigate the existence of solutions for two fractional q -differential inclusions under some integral boundary value conditions. By providing an example, we illustrate our main result about endpoint. Also, we give some related algorithms and numerical results.

Keywords: Approximate Endpoint; Boundary Value Condition; Caputo q -Derivation; Fractional q -Differential Inclusion.

1. INTRODUCTION

In 1910, Jackson introduced the subject of q -difference equations.¹ Later, many researchers studied q -difference equations.^{2–13} On the other hand, many modern works recently appeared on integro-differential equations by using different views and fractional derivatives which young researchers could use the works (see, for example Refs. 14–27).

In 2012, Ahmad *et al.* studied the existence and uniqueness of solutions for the fractional q -difference equations ${}^c D_q^\alpha u(t) = T(t, u(t))$ with boundary conditions $\alpha_1 u(0) - \beta_1 D_q u(0) = \gamma_1 u(\eta_1)$ and $\alpha_2 u(1) - \beta_2 D_q u(1) = \gamma_2 u(\eta_2)$, where $\alpha \in (1, 2]$, $\alpha_i, \beta_i, \gamma_i, \eta_i$ are real numbers, for $i = 1, 2$ and $T \in C(J \times \mathbb{R}, \mathbb{R})$.⁶ In 2013, Zhao *et al.* reviewed the q -integral problem $(D_q^\alpha u)(t) + f(t, u(t)) = 0$ with boundary conditions $u(1) = \mu I_q^\beta u(\eta)$ and $u(0) = 0$ for almost all $t \in (0, 1)$, where $q \in (0, 1)$, $\alpha \in (1, 2]$, $\beta \in (0, 2]$, $\eta \in (0, 1)$, μ is positive real number, D_q^α is the q -derivative of Riemann–Liouville and real-values continuous map u defined on $I \times [0, \infty)$.¹³ In 2014, Ahmad *et al.* investigated the problem ${}^c D_q^\beta ({}^c D_q^\gamma + \lambda)u(t) = pf(t, u(t)) + kI_q^\xi g(t, u(t))$ with boundary conditions $\alpha_1 u(0) - \beta_1 (t^{1-\gamma}) D_q u(0)|_{t=0} = \sigma_1 u(\eta_1)$ and $\alpha_2 u(1) + \beta_2 D_q u(1) = \sigma_2 u(\eta_2)$, where $t, q \in [0, 1]$, ${}^c D_q^\beta$ is the fractional Caputo q -derivative, $0 < \beta, \gamma \leq 1$, $I_q^\xi(\cdot)$ denotes the Riemann–Liouville integral with $\xi \in (0, 1)$, f and g are given continuous functions, λ and p, k are real constants, $\alpha_i, \beta_i, \sigma_i \in \mathbb{R}$ and $\eta_i \in (0, 1)$ for $i = 1, 2$.⁵ In 2019, Samei *et al.* reviewed the existence of solutions for some multi-term q -integro-differential equations with nonseparated and initial boundary conditions.¹¹

Now, by using main idea of the papers, we investigate the fractional q -differential inclusion

$${}^c D_q^\alpha u(t) \in T(t, u(t), u'(t), u''(t)), \quad (1.1)$$

with integral boundary conditions

$$\begin{aligned} &u(0) + u(p) + u(1) \\ &= \int_0^1 f_0(s, u(s)) ds, \\ &{}^c D_q^\beta u(0) + {}^c D_q^\beta u(p) + {}^c D_q^\beta u(1) \\ &= \int_0^1 f_1(s, u(s)) ds, \\ &{}^c D_q^\gamma u(0) + {}^c D_q^\gamma u(p) + {}^c D_q^\gamma u(1) \\ &= \int_0^1 f_2(s, u(s)) ds, \end{aligned} \quad (1.2)$$

where $t \in J = [0, 1]$, $\alpha \in (2, 3]$, $0 < q, p, \beta < 1$, $\gamma \in (1, 2)$, the maps $f_1, f_2, f_3 : J \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous, $T : J \times \mathbb{R}^3 \rightarrow P_{cp}(\mathbb{R})$ is a multifunction and ${}^c D_q^\beta$ is the fractional Caputo q -derivation. Denote the set of all compact subsets of \mathbb{R} by $P_{cp}(\mathbb{R})$. Also, we study the existence of solutions for the fractional q -differential inclusion problem

$$\begin{aligned} &{}^c D_q^\alpha u(t) \\ &\in T(t, u(t), {}^c D_q^{\gamma_1} u(t), \dots, {}^c D_q^{\gamma_n} u(t)), \end{aligned} \quad (1.3)$$

with boundary conditions

$$\begin{aligned} &u'(0) + a_1 u'(1) = \sum_{i=1}^n {}^c D_q^{\gamma_i} u(p), \\ &u(0) + a_2 u(1) = \sum_{i=1}^n I_q^{\gamma_i} u(p), \end{aligned} \quad (1.4)$$

where $t \in J$, $\alpha \in (1, 2]$, $0 < q, p, \gamma_i < 1$, $\alpha - \gamma_i \in [1, \infty)$ for all $1 \leq i \leq n$, $a_1 > \sum_{i=1}^n \frac{p^{1-\gamma_i}}{\Gamma_q(2-\gamma_i)}$, $a_2 > \sum_{i=1}^n \frac{p^{\gamma_i+1}}{\Gamma_q(\gamma_i+2)}$ and $T : J \times \mathbb{R}^{n+1} \rightarrow P(\mathbb{R})$ is a multifunction.

Let $q \in (0, 1)$ and $a \in \mathbb{R}$. Define $[a]_q = \frac{1-q^a}{1-q}$. The power function $(x - y)_q^n$ with $n \in \mathbb{N}_0$ is defined by $(x - y)_q^{(n)} = \prod_{k=0}^{n-1} (x - yq^k)$ for $n \geq 1$ and

$(x - y)_q^{(0)} = 1$, where x and y are real numbers and $\mathbb{N}_0 := \{0\} \cup \mathbb{N}$.² Also, for $\alpha \in \mathbb{R}$ and $a \neq 0$, we have $(x - y)_q^{(\alpha)} = x^\alpha \prod_{k=0}^{\infty} (x - yq^k)/(x - yq^{\alpha+k})$. If $y = 0$, then it is clear that $x^{(\alpha)} = x^\alpha$ (Algorithm 1). The q -Gamma function is given by $\Gamma_q(z) = (1 - q)^{(z-1)}/(1 - q)^{z-1}$, where $z \in \mathbb{R} \setminus \{0, -1, -2, \dots\}$.¹ Note that, $\Gamma_q(z + 1) = [z]_q \Gamma_q(z)$. The value of q -Gamma function, $\Gamma_q(z)$, for input values q and z is derived by counting the number of sentences n in summation by simplifying analysis (check Tables 1–3). For this design, we prepare a pseudo-code description of the technique for estimating q -Gamma function of order n which show in Algorithm 2. The q -derivative of function f , is defined by $(D_q f)(x) = \frac{f(x) - f(qx)}{(1-q)x}$ and $(D_q f)(0) = \lim_{x \rightarrow 0} (D_q f)(x)$ which is shown in Algorithm 3.² Also, the higher order q -derivative of a function f is defined by $(D_q^n f)(x) = D_q(D_q^{n-1} f)(x)$ for all $n \geq 1$, where $(D_q^0 f)(x) = f(x)$.^{2,3} The q -integral of a function f defined on $[0, b]$ is defined by

$$I_q f(x) = \int_0^x f(s) d_q s = x(1 - q) \sum_{k=0}^{\infty} q^k f(xq^k),$$

Algorithm 1. The proposed method for calculated $(a - b)_q^{(\alpha)}$

Input: a, b, α, n, q

- 1: $s \leftarrow 1$
- 2: **if** $n = 0$ **then**
- 3: $p \leftarrow 1$
- 4: **else**
- 5: **for** $k = 0$ to n **do**
- 6: $s \leftarrow s * (a - b * a^k)/(a - b * q^{\alpha+k})$
- 7: **end for**
- 8: $p \leftarrow a^\alpha * s$
- 9: **end if**

Output: $(a - b)_q^{(\alpha)}$

Algorithm 2. The proposed method for calculated $\Gamma_q(x)$

Input: $n, q \in (0, 1), x \in \mathbb{R} \setminus \{0, -1, 2, \dots\}$

- 1: $p \leftarrow 1$
- 2: **for** $k = 0$ to n **do**
- 3: $p \leftarrow p(1 - q^{k+1})(1 - q^{x+k})$
- 4: **end for**
- 5: $\Gamma_q(x) \leftarrow p/(1 - q)^{x-1}$

Output: $\Gamma_q(x)$

for $0 \leq x \leq b$, provided the series absolutely converges.^{2,3} The q -derivative of function f is

Algorithm 3. The proposed method for calculated $(D_q f)(x)$

Input: $q \in (0, 1), f(x), x$

- 1: syms z
- 2: **if** $x = 0$ **then**
- 3: $g \leftarrow \lim((f(z) - f(q * z))/((1 - q)z), z, 0)$
- 4: **else**
- 5: $g \leftarrow (f(x) - f(q * x))/((1 - q)x)$
- 6: **end if**

Output: $(D_q f)(x)$

defined by $(D_q f)(x) = \frac{f(x) - f(qx)}{(1-q)x}$ and $(D_q f)(0) = \lim_{x \rightarrow 0} (D_q f)(x)$ which is shown in Algorithm 3.^{2,3} If a in $[0, b]$, then $\int_a^b f(u) d_q u = I_q f(b) - I_q f(a) = (1 - q) \sum_{k=0}^{\infty} q^k [bf(bq^k) - af(aq^k)]$ whenever the series exists. The operator I_q^n is given by $(I_q^0 h)(x) = h(x)$ and $(I_q^n h)(x) = (I_q(I_q^{n-1} h))(x)$ for $n \geq 1$ and $g \in C([0, b])$.^{2,3} It has been proved that $(D_q(I_q f))(x) = f(x)$ and $(I_q(D_q f))(x) = f(x) - f(0)$ whenever f is continuous at $x = 0$.^{2,3} The fractional Riemann–Liouville-type q -integral of the function f on J for $\alpha \geq 0$ is defined by $(I_q^0 f)(t) = f(t)$ and $(I_q^\alpha f)(t) = \frac{1}{\Gamma_q(\alpha)} \int_0^t (t - qs)^{(\alpha-1)} f(s) d_q s$ for $t \in J$ and $\alpha > 0$.⁸ Also, the Caputo fractional q -derivative of a function f is defined by

$$\begin{aligned} ({}^c D_q^\alpha f)(t) &= (I_q^{[\alpha]-\alpha} (D_q^{[\alpha]} f))(t) \\ &= \frac{1}{\Gamma_q([\alpha] - \alpha)} \\ &\quad \times \int_0^t (t - qs)^{([\alpha]-\alpha-1)} \\ &\quad \times (D_q^{[\alpha]} f)(s) d_q s, \end{aligned} \tag{1.5}$$

where $t \in J$ and $\alpha > 0$.⁸ It has been proved that $(I_q^\beta (I_q^\alpha f))(x) = (I_q^{\alpha+\beta} f)(x)$ and $(D_q^\alpha (I_q^\alpha f))(x) = f(x)$, where $\alpha, \beta \geq 0$.⁸ By using Algorithm 2, we can calculate $(I_q^\alpha f)(x)$ which is shown in Algorithm 4.

Algorithm 4. The proposed method for calculated $(I_q^\alpha f)(x)$

Input: $q \in (0, 1), \alpha, n, f(x), x$

- 1: $s \leftarrow 0$
- 2: **for** $i = 0$ to n **do**
- 3: $pf \leftarrow (1 - q^{i+1})^{\alpha-1}$
- 4: $s \leftarrow s + pf * q^i * f(x * q^i)$
- 5: **end for**
- 6: $g \leftarrow (x^\alpha * (1 - q) * s)/(\Gamma_q(x))$

Output: $(I_q^\alpha f)(x)$

Algorithm 5. The proposed method for calculated $\int_a^b f(r)d_q r$

Input: $q \in (0, 1), \alpha, n, f(x), a, b$

- 1: $s \leftarrow 0$
 - 2: **for** $i = 0 : n$ **do**
 - 3: $s \leftarrow s + q^i * (b * f(b * q^i) - a * f(a * q^i))$
 - 4: **end for**
 - 5: $g \leftarrow (1 - q) * s$
- Output:** $\int_a^b f(r)d_q r$

We say that a multifunction $G: J \rightarrow P_{cl}(\mathbb{R})$ is measurable if the map $t \mapsto d(y, G(t))$ is measurable for each real number y .¹⁴ The Pompeiu–Hausdorff metric $H_d: 2^X \times 2^X \rightarrow [0, \infty)$ on a metric space (X, ρ) is defined by $H_\rho(A, B) = \max\{\sup_{a \in A} \rho(a, B), \sup_{b \in B} \rho(A, b)\}$, where $\rho(A, b) = \inf_{a \in A} \rho(a, b)$.^{14,28} Denote the set of closed and bounded and the set of closed subsets of X by $CB(X)$ and $C(X)$, respectively. Then, $(CB(X), H_\rho)$ is a metric space and $(C(X), H_\rho)$ is a generalized metric space.²⁸ An element $z \in X$ is called an endpoint of multifunction $T: X \rightarrow 2^X$ whenever $Tz = \{z\}$.²⁹ Also, multifunction T has approximate endpoint property whenever $\inf_{x \in X} \sup_{y \in Tx} \rho(x, y) = 0$.²⁹ A function $\theta: \mathbb{R} \rightarrow \mathbb{R}$ is called upper semi-continuous whenever $\limsup_{n \rightarrow \infty} \theta(\lambda_n) \leq \theta(\lambda)$ for all sequence $\{\lambda_n\}_{n \geq 1}$ with $\lambda_n \rightarrow \lambda$.²⁹ In 2010, Amini–Harandi proved the next result.

Lemma 1.1 (Ref. 29). Consider an upper semi-continuous function $\theta: [0, \infty) \rightarrow [0, \infty)$ such that $\theta(t) < t$ and $\liminf_{t \rightarrow \infty} (t - \theta(t)) > 0$, for all $t > 0$. Also, Assume that (X, ρ) is a complete metric space and $T: X \rightarrow CB(X)$ a multifunction such that $H_d(Tx, Ty) \leq \theta(\rho(x, y))$, for all $x, y \in X$. Then T has a unique endpoint if and only if T has approximate endpoint property.

2. MAIN RESULTS

Now, we are ready to state and prove our main results. First, we provide our key result.

Lemma 2.1. Let $v \in C(J, \mathbb{R}), \alpha \in (2, 3], 0 < \beta, q, p < 1, \gamma \in (1, 2)$ and $f_1, f_2: J \times \mathbb{R} \rightarrow \mathbb{R}$ be continuous functions. The unique solution of the fractional q -differential problem

$${}^c D_q^\alpha u(t) = v(t), \tag{2.1}$$

with boundary conditions (1.2) is given by

$$\begin{aligned} u(t) = & I_q^\alpha v(t) + \frac{1}{3} \int_0^1 f_0(s, u(s)) ds \\ & - \frac{1}{3} [I_q^\alpha v(1) + I_q^\alpha v(p)] \\ & + a_1(t) \int_0^1 f_1(s, u(s)) ds \\ & + a_2(t) [I_q^{\alpha-\beta} v(1) + I_q^{\alpha-\beta} v(p)] \\ & + (b_1 + a_3(t)) \int_0^1 g_2(s, u(s)) ds \\ & + (b_2 + a_4(t)) [I_q^{\alpha-\gamma} v(1) + I_q^{\alpha-\gamma} v(p)], \end{aligned} \tag{2.2}$$

where

$$\begin{aligned} a_1(t) &= \frac{3t\Gamma_q(2-\beta) - (p+1)\Gamma_q(2-\beta)}{3(p^{1-\beta} + 1)}, \\ a_2(t) &= \frac{(p+1)\Gamma_q(2-\beta) - 3\Gamma_q(2-\beta)t}{3(p^{1-\beta} + 1)}, \\ a_3(t) &= \frac{-6(p^{2-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(2-\beta)t}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)} \\ &+ \frac{3(p^{1-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(3-\beta)t^2}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)}, \\ a_4(t) &= \frac{6(p^{2-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(2-\beta)t}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)} \\ &- \frac{3\Gamma_q(3-\gamma)\Gamma_q(3-\beta)(p^{1-\beta} + 1)t^2}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)}, \\ b_1 &= \frac{2(p+1)(p^{2-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(2-\beta)}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)} \\ &- \frac{(p^2 + 1)\Gamma_q(3-\gamma)(p^{1-\beta} + 1)\Gamma_q(3-\beta)}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)}, \\ b_2 &= \frac{(p^2 + 1)\Gamma_q(3-\gamma)(p^{1-\beta} + 1)\Gamma_q(3-\beta)}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)} \\ &- \frac{2(p+1)(p^{2-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(2-\beta)}{6(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)}. \end{aligned} \tag{2.3}$$

Proof. It is known that the general solution of Eq. (2.1) is given by

$$\begin{aligned} u(t) = & \frac{1}{\Gamma_q(\alpha)} \int_0^t (t - qs)^{(\alpha-1)} v(s) d_qs \\ & + c_0 + c_1 t + c_2 t^2, \end{aligned} \tag{2.4}$$

where c_0, c_1 and c_2 are real constants.^{14,28} Thus, ${}^c D_q^\beta u(t) = I_q^{\alpha-\beta} v(t) + \frac{c_1 t^{1-\beta}}{\Gamma_q(2-\beta)} + \frac{2c_2 t^{2-\beta}}{\Gamma_q(3-\beta)}$ and ${}^c D_q^\gamma u(t) = I_q^{\alpha-\gamma} v(t) + \frac{2c_2 t^{2-\gamma}}{\Gamma_q(3-\gamma)}$. Thus, we get

$$\begin{aligned} & u(0) + u(p) + u(1) \\ &= 3c_0 + (1+p)c_1 + (1+p^2)c_2 \\ & \quad + I_q^\alpha v(1) + I_q^\alpha v(p), \end{aligned}$$

and

$$\begin{aligned} & {}^c D_q^\beta u(0) + {}^c D_q^\beta u(p) + {}^c D_q^\beta u(1) \\ &= c_1 \frac{p^{1-\beta} + 1}{\Gamma_q(2-\beta)} + c_2 \frac{2(p^{2-\beta} + 1)}{\Gamma_q(3-\beta)} \\ & \quad + I_q^{\alpha-\beta} v(1) + I_q^{\alpha-\beta} v(p), \\ & {}^c D_q^\gamma u(0) + {}^c D_q^\gamma u(p) + {}^c D_q^\gamma u(1) \\ &= c_2 \frac{2(p^{2-\gamma} + 1)}{\Gamma_q(3-\gamma)} + I_q^{\alpha-\gamma} v(1) + I_q^{\alpha-\gamma} v(p). \end{aligned}$$

By using the boundary conditions, we obtain

$$\begin{aligned} & 3c_0 + (1+p)c_1 + (1+p^2)c_2 \\ &= \int_0^1 f_0(s, u(s)) ds - I_q^\alpha v(1) - I_q^\alpha v(p), \\ & c_1 \frac{p^{1-\beta} + 1}{\Gamma_q(2-\beta)} + c_2 \frac{2(p^{2-\beta} + 1)}{\Gamma_q(3-\beta)} \\ &= \int_0^1 f_1(s, x(s)) ds - I_q^{\alpha-\beta} v(1) \\ & \quad - I_q^{\alpha-\beta} v(p), \\ & c_2 \frac{2(p^{2-\gamma} + 1)}{\Gamma_q(3-\gamma)} \\ &= \int_0^1 f_2(s, x(s)) ds - I_q^{\alpha-\gamma} v(1) \\ & \quad - I_q^{\alpha-\gamma} v(p), \end{aligned}$$

and so

$$\begin{aligned} c_0 &= \frac{1}{3} \int_0^1 f_0(s, u(s)) ds - \frac{1}{3} [I_q^\alpha v(1) + I_q^\alpha v(p)] \\ & \quad - \frac{\Gamma_q(2-\beta)(p+1)}{3(p^{1-\beta} + 1)} \int_0^1 f_1(s, u(s)) ds \\ & \quad + \frac{(p+1)\Gamma_q(2-\beta)}{3(p^{1-\beta} + 1)} [I_q^{\alpha-\beta} v(1) + I_q^{\alpha-\beta} v(p)] \\ & \quad + b_1 \int_0^1 f_2(s, u(s)) ds \end{aligned}$$

$$\begin{aligned} & + b_2 [I_q^{\alpha-\gamma} v(1) + I_q^{\alpha-\gamma} v(p)], \\ c_1 &= \frac{\Gamma_q(2-\beta)}{(p^{1-\beta} + 1)} \int_0^1 f_1(s, u(s)) ds - \frac{\Gamma_q(2-\beta)}{(p^{1-\beta} + 1)} \\ & \quad \times [I_q^{\alpha-\beta} v(1) + I_q^{\alpha-\beta} v(p)] \\ & \quad - \frac{(p^{2-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(2-\beta)}{(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)} \\ & \quad \times \int_0^1 f_2(s, u(s)) ds \\ & \quad + \frac{(p^{2-\beta} + 1)\Gamma_q(3-\gamma)\Gamma_q(2-\beta)}{(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3-\beta)} \\ & \quad \times [I_q^{\alpha-\gamma} v(1) + I_q^{\alpha-\gamma} v(p)], \\ c_2 &= \frac{\Gamma_q(3-\gamma)}{2(p^{2-\gamma} + 1)} \int_0^1 f_2(s, u(s)) ds \\ & \quad - \frac{\Gamma_q(3-\gamma)}{2(p^{2-\gamma} + 1)} [I_q^{\alpha-\gamma} v(1) + I_q^{\alpha-\gamma} v(p)]. \end{aligned}$$

On the other hand, by some calculations, one could get the given map u is a solution for the problem. This completes the proof. \square

Assume that $\mathcal{X} = C^2(J)$ is endowed with the norm $\|u\| = \sup_{t \in J} |u(t)| + \sup_{t \in J} |u'(t)| + \sup_{t \in J} |u''(t)|$. Then $(\mathcal{X}, \|\cdot\|)$ is a Banach space. For $u \in \mathcal{X}$, we define the selection set $S_{T,u}$ by the set of all $v \in L^1(J)$ somehow that $v(t) \in T(t, u(t), u'(t), u''(t))$ for all $t \in J$ (see Ref. 14). To study the problem (1.1) and (1.2), we consider the next conditions.

- (C1) The multifunction $T : J \times \mathbb{R}^3 \rightarrow P_{cp}(\mathbb{R})$ is integrable bounded and $T(\cdot, x_1, x_2, x_3) : J \rightarrow P_{cp}(\mathbb{R})$ is measurable for all $x_i \in \mathbb{R}$.
- (C2) The functions f_1, f_2 and $f_3 : J \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous and the map $\theta : [0, \infty) \rightarrow [0, \infty)$ is nondecreasing and upper semi-continuous with $\liminf_{t \rightarrow \infty} (t - \theta(t)) > 0$ and $\theta(t) < t$ for all $t > 0$.
- (C3) There exist $m, m_0, m_1, m_2 \in C(J, [0, \infty))$ such that

$$\begin{aligned} & H_d(T(t, x_1, x_2, x_3), \\ & T(t, x'_1, x'_2, x'_3)) \leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m(t)\theta \\ & \quad \times \left(\sum_{k=1}^3 |x_k - x'_k| \right), \end{aligned}$$

and $|f_j(t, x) - f_j(t, x')| \leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m_j(t) \psi(|x - x'|)$, for all $t \in J, x, x', x_i, x'_i \in \mathbb{R}$, where

$$\Lambda_1 = \left[\frac{\|m\|_\infty}{\Gamma_q(\alpha + 1)} + \frac{\|m_0\|_\infty}{3} + \frac{2\|m\|_\infty}{3\Gamma_q(\alpha + 1)} + \frac{5\Gamma_q(2 - \beta)\|m_1\|_\infty}{3} + \frac{10\Gamma_q(2 - \beta)\|m\|_\infty}{3\Gamma_q(\alpha - \beta + 1)} + 10(2\Gamma_q(2 - \beta) + \Gamma_q(3 - \beta)) \times \left(\frac{\Gamma_q(3 - \gamma)(\|m_2\|_\infty \times \Gamma_q(\alpha - \gamma + 1) + 2\|m\|_\infty)}{3\Gamma_q(3 - \beta)\Gamma_q(\alpha - \gamma + 1)} \right) \right],$$

$$\Lambda_2 = \left[\frac{\|m\|_\infty}{\Gamma_q(\alpha)} + \frac{2\Gamma_q(2 - \beta)\|m\|_\infty}{\Gamma_q(\alpha - \beta + 1)} + (2\Gamma_q(2 - \beta) + \Gamma_q(3 - \beta)) \times \left(\frac{\Gamma_q(3 - \gamma)(\|m_2\|_\infty \times \Gamma_q(\alpha - \gamma + 1) + 2\|m\|_\infty)}{\Gamma(3 - \beta)\Gamma_q(\alpha - \gamma + 1)} \right) \right],$$

$$\Lambda_3 = \left[\frac{\|m\|_\infty}{\Gamma_q(\alpha - 1)} + \frac{\Gamma_q(3 - \gamma)(\|m_2\|_\infty \Gamma_q(\alpha - \gamma + 1) + 2\|m\|_\infty)}{\Gamma_q(\alpha - \gamma + 1)} \right].$$

Define the multifunction $N : \mathcal{X} \rightarrow 2^{\mathcal{X}}$ by

$$N(u) = \{h \in \mathcal{X} \mid \exists v \in S_{T,u} \text{ such that } h(t) = w(t) \text{ for all } t \in J\},$$

where

$$w(t) = I_q^\alpha v(t) + \frac{1}{3} \int_0^1 f_0(s, u(s)) ds - \frac{1}{3} [I_q^\alpha v(1) + I_q^\alpha v(p)] + a_1(t) \int_0^1 f_1(s, u(s)) ds + a_2(t) [I_q^{\alpha-\beta} v(1) + I_q^{\alpha-\beta} v(p)] + (b_1 + a_3(t)) \int_0^1 f_2(s, u(s)) ds + (b_2 + a_4(t)) [I_q^{\alpha-\gamma} v(1) + I_q^{\alpha-\gamma} v(p)].$$

Theorem 2.2. *The boundary value q -differential inclusion problems (1.1) and (1.2) has a solution whenever the multifunction $N : \mathcal{X} \rightarrow P(\mathcal{X})$ has the approximate endpoint property and the conditions (C1)–(C3) hold.*

Proof. We show that the multifunction N has an endpoint which is a solution for the problems (1.1) and (1.2). Since the multivalued map $t \mapsto T(t, u(t), u'(t), u''(t))$ is measurable, N has closed values and so has measurable selection. This implies that $S_{T,u}$ is nonempty for all $u \in \mathcal{X}$. Now, we show that $N(u) \subset \mathcal{X}$ is closed for all $u \in \mathcal{X}$. Let $u \in \mathcal{X}$ and $\{x_n\}_{n \geq 1}$ be a sequence in $N(u)$ with $u_n \rightarrow x$. For each $n \in \mathbb{N}$, choose $v_n \in S_{T,u}$ such that

$$x_n(t) = I_q^\alpha v_n(t) + \frac{1}{3} \int_0^1 f_0(s, u(s)) ds - \frac{1}{3} [I_q^\alpha v_n(1) + I_q^\alpha v_n(p)] + a_1(t) \int_0^1 f_1(s, u(s)) ds + a_2(t) [I_q^{\alpha-\beta} v_n(1) + I_q^{\alpha-\beta} v_n(p)] + (b_1 + a_3(t)) \int_0^1 f_2(s, u(s)) ds + (b_2 + a_4(t)) [I_q^{\alpha-\gamma} v_n(1) + I_q^{\alpha-\gamma} v_n(p)].$$

Since T has compact values, $\{v_n\}_{n \geq 1}$ has a subsequence which converges to some $v \in L^1(J)$. Denote this subsequence by $\{v_n\}_{n \geq 1}$ again. It is easy to check that $v \in S_{T,u}$ and $x_n \rightarrow x$, where

$$x(t) = I_q^\alpha v(t) + \frac{1}{3} \int_0^1 f_0(s, u(s)) ds - \frac{1}{3} [I_q^\alpha v(1) + I_q^\alpha v(p)]$$

$$\begin{aligned}
 &+ a_1(t) \int_0^1 f_1(s, u(s))ds + a_2(t) \\
 &\times [I_q^{\alpha-\beta}v(1) + I_q^{\alpha-\beta}v(p)] \\
 &+ (b_1 + a_3(t)) \int_0^1 f_2(s, u(s))ds \\
 &+ (b_2 + a_4(t))[I_q^{\alpha-\gamma}v(1)I_q^{\alpha-\gamma}v(p)],
 \end{aligned}$$

for all $t \in J$. This implies that $x \in N(u)$ and so N has closed values. Since T has compact values, it is easy to see that $N(u)$ is a bounded set for all $u \in \mathcal{X}$. Now, we show that $H_d(N(u), N(v)) \leq \theta(\|u - v\|)$. Let $u, v \in \mathcal{X}$ and $h_1 \in N(v)$. Choose $w_1 \in S_{T,v}$ such that

$$\begin{aligned}
 h_1(t) &= I_q^\alpha w_1(t) + \frac{1}{3} \int_0^1 f_0(s, v(s))ds \\
 &- \frac{1}{3}[I_q^\alpha w_1(1) + I_q^\alpha w_1(p)] \\
 &+ a_1(t) \int_0^1 f_1(s, v(s))ds \\
 &+ a_2(t)[I_q^{\alpha-\beta}w_1(1) + I_q^{\alpha-\beta}w_1(p)] \\
 &+ (b_1 + a_3(t)) \int_0^1 f_2(s, v(s))ds \\
 &+ (b_2 + a_4(t))[I_q^{\alpha-\gamma}w_1(1) + I_q^{\alpha-\gamma}w_1(p)],
 \end{aligned}$$

for almost all $t \in J$. Put $\tilde{T}_{u(t)} = T(t, u(t), u'(t), u''(t))$ and $\tilde{T}_{v(t)} = T(t, v(t), v'(t), v''(t))$. Since

$$\begin{aligned}
 &H_d(\tilde{T}_{u(t)}, \tilde{T}_{v(t)}) \\
 &\leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m(t)\theta(\|u(t) - v(t)\| \\
 &\quad + |u'(t) - v'(t)| + |u''(t) - v''(t)|),
 \end{aligned}$$

for all $t \in J$, there exists $w \in \tilde{T}_{u(t)}$ such that

$$\begin{aligned}
 |w_1(t) - w| &\leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m(t) \\
 &\quad \times \theta(\|u(t) - v(t)\| + |u'(t) - v'(t)| \\
 &\quad + |u''(t) - v''(t)|), \tag{2.5}
 \end{aligned}$$

for all $t \in J$. Consider the multivalued map $G : J \rightarrow P(\mathbb{R})$ defined the set of all $w \in \mathbb{R}$ such that w satisfies in (2.5). Since w_1 and $\varphi = m\theta(\|u - v\| + |u' - v'| + |u'' - v''|)(\frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3})$ are measurable, the multi-function $G(\cdot) \cap T(\cdot, u(\cdot), u'(\cdot), u''(\cdot))$, is measurable. Now, we can choose $w_2(t) \in T(t, u(t), u'(t), u''(t))$

such that

$$\begin{aligned}
 |w_1(t) - w_2(t)| &\leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m(t) \\
 &\quad \times \psi(\|u(t) - v(t)\| + |u'(t) - v'(t)| \\
 &\quad + |u''(t) - v''(t)|),
 \end{aligned}$$

for all $t \in J$. Consider the element $h_2 \in N(u)$ defined by

$$\begin{aligned}
 h_2(t) &= I_q^\alpha w_2(t) + \frac{1}{3} \int_0^1 f_0(s, u(s))ds \\
 &- \frac{1}{3}[I_q^\alpha w_2(1) + I_q^\alpha w_2(p)] \\
 &+ a_1(t) \int_0^1 f_1(s, u(s))ds \\
 &+ a_2(t)[I_q^{\alpha-\beta}w_2(1) + I_q^{\alpha-\beta}w_2(p)] \\
 &+ (b_1 + a_3(t)) \int_0^1 f_2(s, u(s))ds \\
 &+ (b_2 + a_4(t))[I_q^{\alpha-\gamma}w_2(1) + I_q^{\alpha-\gamma}w_2(p)],
 \end{aligned}$$

for all $t \in J$. Then, we have

$$\begin{aligned}
 &|h_1(t) - h_2(t)| \\
 &\leq I_q^\alpha |w_1(t) - w_2(t)| \\
 &\quad + \frac{1}{3} \int_0^1 |f_0(s, v(s)) - f_0(s, u(s))| ds \\
 &\quad + \frac{1}{3}[I_q^\alpha |w_1(1) - w_2(1)| I_q^{\alpha-1} |w_1(p) \\
 &\quad - w_2(p)| ds] + |a_1(t)| \\
 &\quad \times \int_0^1 |f_1(s, v(s)) - f_1(s, u(s))| ds \\
 &\quad + |a_2(t)| [I_q^{\alpha-\beta} |w_1(1) - w_2(1)| \\
 &\quad + I_q^{\alpha-\beta} |w_1(p) - w_2(p)|] + |b_1 + a_3(t)| \\
 &\quad \times \int_0^1 |f_2(s, v(s)) - f_2(s, u(s))| ds \\
 &\quad + |b_2 + a_4(t)| [I_q^{\alpha-\gamma} |w_1(1) - w_2(1)| ds \\
 &\quad + I_q^{\alpha-\gamma} |w_1(p) - w_2(p)| ds] \\
 &\leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} \theta(\|u - v\|)
 \end{aligned}$$

$$\begin{aligned}
 & \times \left[\frac{\|m\|_\infty}{\Gamma_q(\alpha + 1)} + \frac{\|m_0\|_\infty}{3} + \frac{2\|m\|_\infty}{3\Gamma_q(\alpha + 1)} \right. \\
 & + \frac{5\Gamma_q(2 - \beta)\|m_1\|_\infty}{3} + \frac{10\Gamma_q(2 - \beta)\|m\|_\infty}{3\Gamma_q(\alpha - \beta + 1)} \\
 & + 10(2\Gamma_q(2 - \beta) + \Gamma_q(3 - \beta)) \\
 & \left. \times \left(\frac{\Gamma_q(3 - \gamma)(\|m_2\|_\infty \times \Gamma_q(\alpha - \gamma + 1) + 2\|m\|_\infty)}{3\Gamma_q(3 - \beta)\Gamma_q(\alpha - \gamma + 1)} \right) \right] \\
 & = \frac{\Lambda_1}{\Lambda_1 + \Lambda_2 + \Lambda_3} \psi(\|u - v\|), \\
 |h'_1(t) - h'_2(t)| & \leq I_q^{\alpha-1} |w_1(t) - w_2(t)| \\
 & + \frac{\Gamma(2 - \beta)}{(p^{1-\beta} + 1)} [I_q^{\alpha-\beta} |w_1(1) - w_2(1)| \\
 & + I_q^{\alpha-\beta} |w_1(p) - w_2(p)|] + |a_5(t)| \\
 & \times \int_0^1 |f_2(s, v(s)) - f_2(s, u(s))| ds \\
 & + |a_6(t)| [I_q^{\alpha-\gamma} |w_1(1) - w_2(1)| \\
 & + I_q^{\alpha-\gamma-1} |w_1(p) - w_2(p)|] \\
 & \leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} \theta(\|u - v\|) \\
 & \times \left[\frac{\|m\|_\infty}{\Gamma_q(\alpha)} + \frac{2\Gamma_q(2 - \beta)\|m\|_\infty}{\Gamma_q(\alpha - \beta + 1)} \right. \\
 & + (2\Gamma_q(2 - \beta) + \Gamma_q(3 - \beta)) \\
 & \left. \times \left(\frac{\Gamma_q(3 - \gamma)(\|m_2\|_\infty \times \Gamma_q(\alpha - \gamma + 1) + 2\|m\|_\infty)}{\Gamma_q(3 - \beta)\Gamma_q(\alpha - \gamma + 1)} \right) \right] \\
 & = \frac{\Lambda_2}{\Lambda_1 + \Lambda_2 + \Lambda_3} \theta(\|u - v\|),
 \end{aligned}$$

and

$$\begin{aligned}
 & |h''_1(t) - h''_2(t)| \\
 & \leq I_q^{\alpha-2} |w_1(t) - w_2(t)| \\
 & + \frac{\Gamma_q(3 - \gamma)}{(p^{2-\gamma} + 1)} \int_0^1 |f_2(s, v(s)) - f_2(s, u(s))| ds \\
 & + \frac{\Gamma_q(3 - \gamma)}{(p^{2-\gamma} + 1)} [I_q^{\alpha-\gamma} |w_1(1) - w_2(1)| \\
 & + I_q^{\alpha-\gamma} |w_1(p) - w_2(p)|] \\
 & \leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} \psi(\|u - v\|) \\
 & \times \left[\frac{\Gamma_q(3 - \gamma)(\|m_2\|_\infty \times \Gamma_q(\alpha - \gamma + 1) + 2\|m\|_\infty)}{\Gamma_q(\alpha - 1) + \Gamma_q(\alpha - \gamma + 1)} \right] \\
 & = \frac{\Lambda_3}{\Lambda_1 + \Lambda_2 + \Lambda_3} \psi(\|u - v\|),
 \end{aligned}$$

where

$$\begin{aligned}
 a_5(t) & = \frac{(p^{2-\beta} + 1)\Gamma_q(3 - \gamma)\Gamma_q(2 - \beta)}{(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3 - \beta)} \\
 & + \frac{\Gamma_q(3 - \gamma)(p^{1-\beta} + 1)\Gamma_q(3 - \beta)t}{(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3 - \beta)}, \\
 a_6(t) & = \frac{(p^{2-\beta} + 1)\Gamma_q(3 - \gamma)\Gamma_q(2 - \beta)}{(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3 - \beta)\Gamma_q(\alpha - \gamma)} \\
 & - \frac{\Gamma_q(3 - \gamma)\Gamma_q(3 - \beta)(p^{1-\beta} + 1)t}{(p^{1-\beta} + 1)(p^{2-\gamma} + 1)\Gamma_q(3 - \beta)\Gamma_q(\alpha - \gamma)}.
 \end{aligned}$$

Hence,

$$\begin{aligned}
 \|h_1 - h_2\| & = \sup_{t \in J} |h_1(t) - h_2(t)| \\
 & + \sup_{t \in J} |h'_1(t) - h'_2(t)| \\
 & + \sup_{t \in J} |h''_1(t) - h''_2(t)| \\
 & \leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} \theta \\
 & \times (\|x - y\|)(\Lambda_1 + \Lambda_2 + \Lambda_3) \\
 & = \theta(\|x - y\|).
 \end{aligned}$$

Thus, $H_d(N(u), N(v)) \leq \theta(\|u - v\|)$ for all $u, v \in \mathcal{X}$. On the other hand, the multifunction N has approximate endpoint property. By using Lemma 1.1,

there exists $u^* \in \mathcal{X}$ such that $N(u^*) = \{u^*\}$. By using Lemma 2.1, u^* is a solution for the problems (1.1) and (1.2). \square

Now, we investigate the existence of solution for the fractional q -differential inclusion problem with integral boundary value conditions

$$\begin{aligned} {}^c D_q^\alpha u(t) &\in T(t, u(t), {}^c D_q^{\gamma_1} u(t), \\ &\quad \dots, {}^c D_q^{\gamma_n} u(t)), \\ u'(0) + a_1 u'(1) &= \sum_{i=1}^n {}^c D_q^{\gamma_i} u(p), \\ u(0) + a_2 u(1) &= \sum_{i=1}^n I_q^{\beta_i} u(p), \end{aligned} \tag{2.6}$$

where $T : J \times \mathbb{R}^{n+1} \rightarrow P(\mathbb{R})$ is a multifunction, $t \in J$, $\alpha \in (1, 2]$, $n \geq 2$, $0 < q, p, \gamma_i < 1$, $\alpha - \gamma_i \geq 1$ for all $1 \leq i \leq n$, $a_1 > \sum_{i=1}^n \frac{p^{1-\gamma_i}}{\Gamma_q(2-\gamma_i)}$ and $a_2 > \sum_{i=1}^n \frac{p^{\gamma_i+1}}{\Gamma_q(\gamma_i+2)}$.

Lemma 2.3. *Let $v \in C(J, \mathbb{R})$, $1 < \alpha \geq 2$, $0 < q, p < 1$, $n \geq 2$ and $0 < \beta_i < 1$ for $i = 1, \dots, n$. The unique solution of the fractional q -differential problem with the boundary value conditions*

$$\begin{cases} {}^c D_q^\alpha u(t) = v(t), \\ x'(0) + a_1 u'(1) = \sum_{i=1}^n {}^c D_q^{\beta_i} u(p), \\ x(0) + a_2 u(1) = \sum_{i=1}^n I_q^{\beta_i} u(p), \end{cases} \tag{2.7}$$

is given by $u(t) = \int_0^1 G(t, s)v(s)ds$, where $a_1 > \sum_{i=1}^n \frac{p^{1-\beta_i}}{\Gamma_q(2-\beta_i)}$, $a_2 > \sum_{i=1}^n \frac{p^{\beta_i+1}}{\Gamma_q(\beta_i+2)}$ and $G(t, s)$ is the Green function given by

$$\begin{aligned} G(t, s) &= \frac{(t - qs)^{(\alpha-1)}}{\Gamma_q(\alpha)} \\ &+ \frac{1}{A} \sum_{i=1}^n \frac{(p - qs)^{(\alpha+\beta_i-1)}}{\Gamma_q(\alpha + \beta_i)} \\ &- \frac{a_2}{A\Gamma_q(\alpha)}(1 - qs)^{(\alpha-1)} - \frac{1}{AB} \\ &\times \left(a - \sum_{i=1}^n \frac{p^{\beta_i+2}}{\Gamma_q(\beta_i + 3)} \right) \end{aligned}$$

$$\begin{aligned} &\times \sum_{i=1}^n \frac{(p - qs)^{(\alpha-\beta_i-1)}}{\Gamma_q(\alpha - \beta_i)} \\ &- \frac{a_1}{AB} \left(a - \sum_{i=1}^n \frac{p^{\beta_i+2}}{\Gamma_q(\beta_i + 3)} \right) \frac{(1 - qs)^{(\alpha-2)}}{\Gamma_q(\alpha - 1)} \\ &+ \frac{t}{B} \sum_{i=1}^n \frac{(p - qs)^{(\alpha-\beta_i-1)}}{\Gamma_q(\alpha - \beta_i)} \\ &- \frac{a_1 t}{B\Gamma_q(\alpha - 1)}(1 - qs)^{(\alpha-2)}, \end{aligned}$$

whenever $0 \leq s \leq p \leq t \leq 1$,

$$\begin{aligned} G(t, s) &= \frac{(t - qs)^{(\alpha-1)}}{\Gamma_q(\alpha)} \\ &- \frac{a_2}{A\Gamma_q(\alpha)}(1 - qs)^{(\alpha-1)} \\ &- \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i+2}}{\Gamma_q(\beta_i + 3)} \right) \\ &\times \frac{(1 - qs)^{(\alpha-2)}}{\Gamma_q(\alpha - 1)} \\ &- \frac{a_1 t}{B\Gamma_q(\alpha - 1)}(1 - qs)^{(\alpha-2)}, \end{aligned}$$

whenever $0 \leq p \leq s \leq t \leq 1$,

$$\begin{aligned} G(t, s) &= -\frac{a_2}{A\Gamma_q(\alpha)}(1 - qs)^{(\alpha-1)} \\ &- \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i+2}}{\Gamma_q(\beta_i + 3)} \right) \\ &\times \frac{(1 - qs)^{(\alpha-2)}}{\Gamma_q(\alpha - 1)} \\ &- \frac{a_1 t}{B\Gamma_q(\alpha - 1)}(1 - qs)^{(\alpha-2)}, \end{aligned}$$

whenever $0 \leq p \leq s \leq t \leq 1$,

$$\begin{aligned} G(t, s) &= \frac{(t - qs)^{(\alpha-1)}}{\Gamma_q(\alpha)} \\ &+ \frac{1}{A} \sum_{i=1}^n \frac{(p - qs)^{(\alpha+\beta_i-1)}}{\Gamma_q(\alpha + \beta_i)} \\ &- \frac{a_2}{A\Gamma_q(\alpha)}(1 - qs)^{(\alpha-1)} \\ &- \frac{1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i+2}}{\Gamma_q(\beta_i + 3)} \right) \end{aligned}$$

$$\begin{aligned} & \times \sum_{i=1}^n \frac{(p - qs)^{(\alpha - \beta_i - 1)}}{\Gamma_q(\alpha - \beta_i)} \\ & - \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma(\beta_i + 3)} \right) \\ & \times \frac{(1 - qs)^{(\alpha - 2)}}{\Gamma_q(\alpha - 1)} \\ & + \frac{t}{B} \sum_{i=1}^n \frac{(p - qs)^{(\alpha - \beta_i - 1)}}{\Gamma_q(\alpha - \beta_i)} \\ & - \frac{a_1 t}{B\Gamma_q(\alpha - 1)} (1 - qs)^{(\alpha - 2)}, \end{aligned}$$

whenever $0 \leq s \leq t \leq p \leq 1$,

$$\begin{aligned} G(t, s) &= \frac{1}{A} \sum_{i=1}^n \frac{(p - qs)^{(\alpha + \beta_i - 1)}}{\Gamma_q(\alpha + \beta_i)} \\ & - \frac{a_2}{A\Gamma_q(\alpha)} (1 - qs)^{(\alpha - 1)} \\ & - \frac{1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) \\ & \times \sum_{i=1}^n \frac{(p - qs)^{(\alpha - \beta_i - 1)}}{\Gamma_q(\alpha - \beta_i)} \\ & - \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) \\ & \times \frac{(1 - qs)^{(\alpha - 2)}}{\Gamma_q(\alpha - 1)} + \frac{t}{B} \sum_{i=1}^n \\ & \times \frac{(p - qs)^{(\alpha - \beta_i - 1)}}{\Gamma_q(\alpha - \beta_i)} \\ & - \frac{a_1 t}{B\Gamma_q(\alpha - 1)} (1 - qs)^{(\alpha - 2)}, \end{aligned}$$

whenever $0 \leq s \leq t \leq p \leq 1$ and

$$\begin{aligned} G(t, s) &= -\frac{a_2}{A\Gamma_q(\alpha)} (1 - qs)^{(\alpha - 1)} \\ & - \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) \\ & \times \frac{(1 - qs)^{(\alpha - 2)}}{\Gamma_q(\alpha - 1)} \\ & - \frac{a_1 t}{B\Gamma_q(\alpha - 1)} (1 - qs)^{(\alpha - 2)}, \end{aligned}$$

whenever $0 \leq t \leq p \leq s \leq 1$. Here, $A = 1 + a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 1}}{\Gamma_q(\beta_i + 2)}$ and $B = 1 + a_1 - \sum_{i=1}^n \frac{p^{1 - \beta_i}}{\Gamma_q(2 - \beta_i)}$.

Proof. It is known that the solution of ${}^c D_q^\alpha u(t) = v(t)$ is given by

$$\begin{aligned} u(t) &= I_q^\alpha v(t) + c_0 + c_1 t \\ &= \frac{1}{\Gamma_q(\alpha)} \int_0^t (t - qs)^{(\alpha - 1)} v(s) ds + c_0 + c_1 t, \end{aligned}$$

where $c_0, c_1 \in \mathbb{R}$ are real constants.^{14,28} Thus, we have ${}^c D_q^{\beta_i} u(t) = I_q^{\alpha - \beta_i} v(t) + \frac{c_1 t^{1 - \beta_i}}{\Gamma_q(2 - \beta_i)}$, $I_q^{\beta_i} u(t) = I_q^{\alpha + \beta_i} v(t) + \frac{c_0 t^{1 + \beta_i}}{\Gamma_q(2 + \beta_i)} + \frac{c_1 t^{2 + \beta_i}}{\Gamma_q(3 + \beta_i)}$ and $u'(t) = I_q^{\alpha - 1} v(t) + c_1$. Hence, $u(0) + a_2 u(1) = (a_2 + 1)c_0 + a_2 c_1 + a_2 I_q^\alpha v(1)$ and $u'(0) + a_1 u'(1) = (1 + a_1)c_1 + a_1 I_q^{\alpha - 1} v(1)$. By using the boundary conditions, we get $c_0(1 + a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 1}}{\Gamma_q(\beta_i + 2)}) + c_1(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)}) = \sum_{i=1}^n I_q^{\alpha + \beta_i} v(p) - a_2 I_q^\alpha v(1)$ and $c_1(1 + a_1 - \sum_{i=1}^n \frac{p^{1 - \beta_i}}{\Gamma_q(2 - \beta_i)}) = \sum_{i=1}^n I_q^{\alpha - \beta_i} v(p) - a_1 I_q^{\alpha - 1} v(1)$. Thus,

$$\begin{aligned} c_0 &= \frac{1}{A} \sum_{i=1}^n I_q^{\alpha + \beta_i} v(p) - \frac{a_2}{A} I_q^\alpha v(1) \\ & - \frac{1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) \sum_{i=1}^n I_q^{\alpha - \beta_i} v(p) \\ & - \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) I_q^{\alpha - 1} v(1), \end{aligned}$$

and $c_1 = \frac{1}{B} \sum_{i=1}^n I_q^{\alpha - \beta_i} v(p) - \frac{a_1}{B} I_q^{\alpha - 1} v(1)$. Hence,

$$\begin{aligned} u(t) &= I_q^\alpha v(t) + \frac{1}{A} \sum_{i=1}^n I_q^{\alpha + \beta_i} v(p) - \frac{a_2}{A} I_q^\alpha v(1) \\ & - \frac{1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) \\ & \times \sum_{i=1}^n I_q^{\alpha - \beta_i} v(p) \\ & - \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\beta_i + 2}}{\Gamma_q(\beta_i + 3)} \right) \end{aligned}$$

$$\begin{aligned} & \times I_q^{\alpha-1}v(1) + \frac{t}{B} \sum_{i=1}^n I_q^{\alpha-\beta_i}v(p) \\ & - \frac{ta_1}{B} I_q^{\alpha-1}v(1) \\ & = \int_0^1 G(t, s)v(s)ds. \end{aligned}$$

The converse part concludes by some calculation. This completes the proof. \square

Consider the Banach space $\mathcal{A} = \{u | u, {}^cD_q^{\gamma_i}u \in C(J, \mathbb{R}) : \forall i = 1, 2, \dots, n\}$ endowed with the norm

$$\|u\| = \sup_{t \in J} |u(t)| + \sum_{i=1}^n \sup_{t \in J} |{}^cD_q^{\gamma_i}u(t)|.$$

Define $S_{T,u} = \{v \in L^1(J) | v(t) \in T(t, u(t), {}^cD_q^{\gamma_1}u(t), \dots, {}^cD_q^{\gamma_n}u(t))\}$ for all $t \in J$ and $u \in \mathcal{A}$. For $1 \leq j \leq n$, put

$$\begin{aligned} L_1 &= \frac{1}{\Gamma_q(\alpha + 1)} + \frac{1}{A} \sum_{i=1}^n \frac{p^{\alpha+\gamma_i}}{\Gamma_q(\alpha + \gamma_i + 1)} \\ &+ \frac{a_2}{A\Gamma_q(\alpha + 1)} + \frac{1}{AB} \left| a - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i + 3)} \right| \\ &\times \sum_{i=1}^n \frac{p^{\alpha-\gamma_i}}{\Gamma_q(\alpha - \gamma_i + 1)} + \frac{a_1}{AB\Gamma_q(\alpha)} \\ &\times \left| a_2 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i + 3)} \right| \\ &+ \frac{1}{B} \sum_{i=1}^n \frac{p^{\alpha-\gamma_i}}{\Gamma_q(\alpha - \gamma_i + 1)} + \frac{a_1}{B\Gamma_q(\alpha)}, \end{aligned}$$

and $L_2^j = \frac{1}{\Gamma_q(\alpha-\gamma_j+1)} + \frac{1}{B\Gamma_q(2-\gamma_j)} \sum_{i=1}^n \frac{p^{\alpha-\gamma_i}}{\Gamma_q(\alpha-\gamma_i+1)} + \frac{a_1}{B\Gamma_q(2-\gamma_j)\Gamma_q(\alpha)}$.

Theorem 2.4. Let the nondecreasing map $\theta : [0, \infty) \rightarrow [0, \infty)$ be an upper semi-continuous such that $\theta(t) < t$ and $\liminf_{t \rightarrow \infty} (t - \theta(t)) > 0$ for all $t > 0$ and $T : J \times \mathbb{R}^{n+1} \rightarrow P_{cp}(\mathbb{R})$ a multifunction such that $T(\cdot, u_1, u_2, \dots, u_{n+1}) : J \rightarrow P_{cp}(\mathbb{R})$ is measurable and bounded integrable for all $u_1, u_2, \dots, u_{n+1} \in \mathbb{R}$. Put $\tilde{T}_{t,u_i} = T(t, u_1, u_2, \dots, u_{n+1})$, $\tilde{T}_{t,v_i} = T(t, v_1, v_2, \dots, v_{n+1})$ and assume that there exists $m \in C(J, [0, \infty))$ such

that

$$\begin{aligned} H_d(\tilde{T}_{t,u_i} - \tilde{T}_{t,v_i}) &\leq m(t)\psi \left(\sum_{i=1}^{n+1} |u_i - v_i| \right) \\ &\times \left(\frac{1}{\|m\|_\infty (L_1 + \sum_{j=1}^n L_2^j)} \right). \end{aligned}$$

Then the inclusion problem (1.3), (1.4) has a solution whenever multifunction $\Omega : \mathcal{A} \rightarrow 2^{\mathcal{A}}$ define by $\Omega(u) = \{h \in \mathcal{A} | \exists v \in S_{T,u} : h(t) = \int_0^1 G(t, s)v(s)ds, \forall t \in J\}$ has the approximate endpoint property.

Proof. We show that the multifunction $\Omega : \mathcal{A} \rightarrow P(\mathcal{A})$ has an endpoint which is a solution for the problem (1.3) and (1.4). First, we show that $\Omega(u)$ is closed for all $u \in \mathcal{A}$. Let $u \in \mathcal{A}$ and $\{x_n\}_{n \geq 1}$ be a sequence in $\Omega(u)$ with $x_n \rightarrow x$. For each n , choose $w_n \in S_{T,u}$ such that

$$x_n(t) = \int_0^1 G(t, s)w_n(s)ds,$$

for all $t \in J$. Since F has compact values, $\{w_n\}_{n \geq 1}$ has a subsequence which converges to some $w \in L^1(J)$. We denote this subsequence again by $\{w_n\}_{n \geq 1}$. It is easy to check that $w \in S_{T,u}$ and $x_n(t) \rightarrow x(t) = \int_0^1 G(t, s)w(s)ds$ for all $t \in J$. This implies that $x \in \Omega(u)$ and so Ω has closed values. Since T is a compact multivalued map, it is easy to check that $\Omega(u)$ is a bounded set for all $u \in \mathcal{A}$. Now, we show that $H_d(\Omega(u), \Omega(v)) \leq \theta(\|u - v\|)$ for all $u, v \in \mathcal{A}$. Suppose that $u, v \in X$ and $h_1 \in \Omega(v)$. Choose $w_1 \in S_{T,v}$ such that $h_1(t) = \int_0^1 G(t, s)w_1(s)ds$ for almost all $t \in J$. Put $\tilde{T}_{t, {}^cD_q^\gamma u} = T(t, u(t), {}^cD_q^{\gamma_1}u(t), \dots, {}^cD_q^{\gamma_n}u(t))$ and

$$\tilde{T}_{t, {}^cD_q^\gamma v} = T(t, v(t), {}^cD_q^{\gamma_1}v(t), \dots, {}^cD_q^{\gamma_n}v(t)).$$

Let $t \in J$. Since

$$\begin{aligned} & H_d(\tilde{T}_{t, {}^cD_q^\gamma u}, \tilde{T}_{t, {}^cD_q^\gamma v}) \\ & \leq m(t)\psi \left(|u(t) - v(t)| \right. \\ & \quad \left. + \sum_{i=1}^n |{}^cD_q^{\gamma_i}u(t) - {}^cD_q^{\gamma_i}v(t)| \right) \\ & \times \left(\frac{1}{\|m\|_\infty (L_1 + \sum_{j=1}^n L_2^j)} \right), \end{aligned}$$

there exists $w \in T(t, u(t), {}^cD_q^{\gamma_1}u(t), \dots, {}^cD_q^{\gamma_n}u(t))$ such that

$$|w_1(t) - w| \leq m(t)\psi \left(|u(t) - v(t)| + \sum_{i=1}^n |{}^cD_q^{\gamma_i}u(t) - {}^cD_q^{\gamma_i}v(t)| \right) \times \left(\frac{1}{\|m\|_\infty (L_1 + \sum_{j=1}^n L_2^j)} \right). \tag{2.8}$$

Consider the multivalued map $U : J \rightarrow P(\mathbb{R})$, where $U(t)$ is the set of all $w \in \mathbb{R}$ such that w satisfies in (2.8). Since w_1 and

$$\varphi = m\psi \left(|u - v| + \sum_{i=1}^n |{}^cD_q^{\gamma_i}u - {}^cD_q^{\gamma_i}v| \right) \times \left(\frac{1}{\|m\|_\infty (L_1 + \sum_{j=1}^n L_2^j)} \right)$$

are measurable, the multifunction $U(\cdot) \cap T(t, u(\cdot), {}^cD_q^{\gamma_1}u(\cdot), \dots, {}^cD_q^{\gamma_n}u(\cdot))$ is measurable. Choose $w_2(t) \in T(t, u(t), {}^cD_q^{\gamma_1}u(t), \dots, {}^cD_q^{\gamma_n}u(t))$ such that

$$|w_1(t) - w_2(t)| \leq m(t)\theta \left(|u(t) - v(t)| + \sum_{i=1}^n |{}^cD_q^{\gamma_i}u(t) - {}^cD_q^{\gamma_i}v(t)| \right) \times \left(\frac{1}{\|m\|_\infty (L_1 + \sum_{j=1}^n L_2^j)} \right).$$

Now, consider the element $h_2 \in \Omega(u)$ which is defined by $h_2(t) = \int_0^1 G(t, s)w_2(s)ds$. Thus,

$$\begin{aligned} &|h_1(t) - h_2(t)| \\ &= \left| \int_0^1 G(t, s)w_1(s)ds - \int_0^1 G(t, s)w_2(s)ds \right| \\ &= \left| I_q^\alpha w_1(t) + \frac{1}{A} \sum_{i=1}^n I_q^{\alpha+\gamma_i} w_1(p) - \frac{a_2}{A} I_q^\alpha w_1(1) \right. \\ &\quad \left. - \frac{1}{AB} \left(a_1 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i+3)} \right) \sum_{i=1}^n I_q^{\alpha-\gamma_i} w_1(p) \right. \end{aligned}$$

$$\begin{aligned} &\left. - \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i+3)} \right) I_q^{\alpha-1} w_1(1) + \frac{t}{B} \right. \\ &\quad \times \sum_{i=1}^n I_q^{\alpha-\gamma_i} w_1(p) - \frac{ta_2}{B} I_q^{\alpha-1} w_1(1) \\ &\quad \left. - I_q^\alpha w_2(1) - \frac{1}{A} \sum_{i=1}^n I_q^{\alpha+\gamma_i} w_2(p) + \frac{a_1}{A} I_q^\alpha w_2(1) \right. \\ &\quad \left. + \frac{1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i+3)} \right) \sum_{i=1}^n I_q^{\alpha-\gamma_i} w_2(p) \right. \\ &\quad \left. + \frac{a_1}{AB} \left(a_2 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i+3)} \right) \right. \\ &\quad \left. \times I_q^{\alpha-1} w_2(1) - \frac{t}{B} \sum_{i=1}^n I_q^{\alpha-\gamma_i} w_2(p) \right. \\ &\quad \left. + \frac{ta_1}{B} I_q^{\alpha-1} w_2(1) \right| \\ &\leq I_q^\alpha |w_1(t) - w_2(t)| \\ &\quad + \frac{1}{A} \sum_{i=1}^n I_q^{\alpha+\gamma_i} |w_1(p) - w_2(p)| \\ &\quad + \frac{a}{A} I_q^\alpha |w_1(1) - w_2(1)| \\ &\quad + \frac{1}{AB} \left| a_2 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i+3)} \right| \\ &\quad \times \sum_{i=1}^n I_q^{\alpha-\gamma_i} |w_1(p) - w_2(p)| \\ &\quad + \frac{a_1}{AB} \left| a_2 - \sum_{i=1}^n \frac{p^{\gamma_i+2}}{\Gamma_q(\gamma_i+3)} \right| \\ &\quad \times I_q^{\alpha-1} |w_1(1) - w_2(1)| \\ &\quad + \frac{t}{B} \sum_{i=1}^n I_q^{\alpha-\gamma_i} |w_1(p) - w_2(p)| \\ &\quad + \frac{ta_1}{B} I_q^{\alpha-1} |w_1(1) - w_2(1)| \\ &\leq \left(\frac{L_1}{L_1 + \sum_{j=1}^n L_2^j} \right) \psi(\|u - v\|), \end{aligned}$$

and

$$\begin{aligned} &|{}^cD_q^{\gamma_j} h_1(t) - {}^cD_q^{\gamma_j} h_2(t)| \\ &\leq I_q^{\alpha-\gamma_j} |w_1(t) - w_2(t)| + \frac{t^{1-\gamma_j}}{B\Gamma(2-\gamma_j)} \end{aligned}$$

$$\begin{aligned} & \times \sum_{i=1}^n I_q^{\alpha-\gamma_i} |w_1(p) - w_2(p)| \\ & + \frac{a_1 t^{1-\gamma_j}}{B\Gamma(2-\gamma_j)} I_q^{\alpha-1} |w_1(1) - w_2(1)| \\ & \leq \left(\frac{L_2^j}{L_1 + \sum_{j=1}^n \Lambda_2^j} \right) \psi(\|u - v\|), \end{aligned}$$

for all $1 \leq j \leq n$. Hence,

$$\begin{aligned} \|h_1 - h_2\| &= \sup_{t \in J} |h_1(t) - h_2(t)| \\ &+ \sup_{t \in J} \sum_{i=1}^n |{}^c D_q^{\gamma_i} h_1(t) \\ &- {}^c D_q^{\gamma_i} h_2(t)| \\ &\leq \theta(\|u - v\|) \\ &\times \left(\frac{L_1}{L_1 + \sum_{j=1}^n L_2^j} \right. \\ &\left. + \sum_{i=1}^n \frac{L_2^i}{L_1 + \sum_{j=1}^n L_2^j} \right) \\ &= \theta(\|u - v\|). \end{aligned}$$

By interchanging the roles of u, v , we conclude $H_d(\Omega(u), \Omega(v)) \leq \theta(\|u - v\|)$. Since the multifunction Ω has approximate endpoint property, by using Lemma 2.3 there exists $u^* \in \mathcal{A}$ such that $\Omega(u^*) = \{u^*\}$. This completes the proof. \square

Here, we provide an example to illustrate our first main result. In this way, we give a computational technique for checking the problems (1.1) and (1.2). We need to present a simplified analysis could be executed values of the q -Gamma function. To this aim, we consider a pseudo-code description of the method for calculation of the q -Gamma function of order n in Algorithm 2.

Example 2.5. Consider the fractional q -differential inclusion problem

$$\begin{aligned} {}^c D_q^{\frac{9}{4}} u(t) &\in \left[0, \frac{t^2}{100} \sin u(t) \right. \\ &+ \frac{1}{100} \cos u'(t) + \frac{1}{100} \\ &\left. \times \left(\frac{|u''(t)|}{1 + |u''(t)|} \right) \right], \end{aligned} \tag{2.9}$$

with the integral boundary conditions

$$\begin{cases} u(0) + u\left(\frac{3}{4}\right) + u(1) \\ = \int_0^1 \frac{s^2}{20} \cos u(s) ds, \\ {}^c D_q^{\frac{2}{3}} u(0) + {}^c D_q^{\frac{2}{3}} u\left(\frac{3}{4}\right) + {}^c D_q^{\frac{2}{3}} u(1) \\ = \int_0^1 \frac{e^{s^2-1}}{20} \cos u(s) ds, \\ {}^c D_q^{\frac{5}{3}} u(0) + {}^c D_q^{\frac{5}{3}} u\left(\frac{3}{4}\right) + {}^c D_q^{\frac{5}{3}} u(1) \\ = \int_0^1 \frac{2s^3 + 1}{20\pi} \cos u(s) ds, \end{cases} \tag{2.10}$$

where $t \in J = [0, 1]$, $\alpha = \frac{9}{4}$, $\beta = \frac{2}{3}$, $\gamma = \frac{5}{3}$ and $p = \frac{3}{4}$. Consider the map $T : J \times \mathbb{R}^3 \rightarrow P(\mathbb{R})$ define by $T(t, x_1, x_2, x_3) = [0, \frac{t^2}{100} \sin x_1 + \frac{1}{100} \cos x_2 + \frac{1}{100} (\frac{|x_3|}{1+|x_3|})]$. Also, define the maps $f_0, f_1, f_2 : J \times \mathbb{R} \rightarrow \mathbb{R}$ define by $f_0(t, x) = \frac{t^2}{20} \cos x$, $f_1(t, x) = \frac{e^{t^2-1}}{20} \cos x$ and $f_2(t, x) = \frac{2t^3+1}{300\pi} \cos x$. Consider $N : C^2(J) \rightarrow 2^{C^2(J)}$ defined by

$$\begin{aligned} N(u) &= \{h \in C^2(J) \mid \exists v \in S_{T,u} : h(t) \\ &= w(t) \text{ for all } t \in J\}, \end{aligned}$$

where

$$\begin{aligned} w(t) &= I_q^{\frac{9}{4}} v(t) + \frac{1}{3} \int_0^1 \frac{s^2}{20} \cos u(s) ds \\ &- \frac{1}{3} \left[I_q^{\frac{9}{4}} v(1) + I_q^{\frac{9}{4}} v\left(\frac{3}{4}\right) \right] \\ &+ a_1(t) \int_0^1 \frac{e^{s^2-1}}{20} \cos u(s) ds \\ &+ a_2(t) \left[I_q^{\frac{19}{12}} v(1) + I_q^{\frac{19}{12}} v\left(\frac{3}{4}\right) \right] \\ &+ (b_1 + a_3(t)) \int_0^1 \frac{2s^3 + 1}{300\pi} \cos u(s) ds \\ &+ (b_2 + a_4(t)) \left[I_q^{\frac{7}{12}} v(1) + I_q^{\frac{7}{12}} v\left(\frac{3}{4}\right) \right]. \end{aligned}$$

Put

$$\begin{aligned} a_1(t) &= \frac{3\Gamma_q\left(\frac{4}{3}\right)t - \frac{7}{4}\Gamma_q\left(\frac{4}{3}\right)}{3\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)}, \\ a_2(t) &= \frac{\frac{7}{4}\Gamma_q\left(\frac{4}{3}\right) - 3\Gamma_q\left(\frac{4}{3}\right)t}{3\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)}, \end{aligned}$$

$$\begin{aligned}
 a_3(t) &= \frac{-6\left(\left(\frac{3}{4}\right)^{\frac{4}{3}} + 1\right)\Gamma_q\left(\frac{4}{3}\right)\Gamma_q\left(\frac{4}{3}\right)t + 3\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\Gamma_q\left(\frac{4}{3}\right)\Gamma_q\left(\frac{7}{3}\right)t^2}{6\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\Gamma_q\left(\frac{7}{3}\right)}, \\
 a_4(t) &= \frac{6\left(\left(\frac{3}{4}\right)^{\frac{4}{3}} + 1\right)\Gamma_q\left(\frac{4}{3}\right)\Gamma_q\left(\frac{4}{3}\right)t - 3\Gamma_q\left(\frac{4}{3}\right)\Gamma_q\left(\frac{7}{3}\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)t^2}{6\left(\left(\frac{1}{3}\right)^{\frac{1}{3}} + 1\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\Gamma_q\left(\frac{7}{3}\right)}, \\
 b_1 &= \frac{\frac{7}{2}\left(\left(\frac{3}{4}\right)^{\frac{4}{3}} + 1\right)\Gamma_q\left(\frac{4}{3}\right)\Gamma_q\left(\frac{4}{3}\right) - \left(\left(\frac{3}{4}\right)^2 + 1\right)\Gamma_q\left(\frac{4}{3}\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\Gamma_q\left(\frac{7}{3}\right)}{6\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\Gamma_q\left(\frac{7}{3}\right)}, \\
 b_2 &= \frac{\left(\left(\frac{3}{4}\right)^2 + 1\right)\Gamma_q\left(\frac{4}{3}\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right) \times \Gamma_q\left(\frac{7}{3}\right) - \frac{8}{3}\left(\left(\frac{3}{4}\right)^{\frac{4}{3}} + 1\right)\Gamma_q\left(\frac{4}{3}\right)\Gamma_q\left(\frac{4}{3}\right)}{6\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\left(\left(\frac{3}{4}\right)^{\frac{1}{3}} + 1\right)\Gamma_q\left(\frac{7}{3}\right)},
 \end{aligned} \tag{2.11}$$

$m(t) = \frac{3t}{20}$, $m_0(t) = \frac{t^2}{20}$, $m_1(t) = \frac{e^{t^2-1}}{20}$, $m_2(t) = \frac{2t^3+1}{300\pi}$ and $\psi(t) = \frac{t}{5}$. Then, we have

$$\Lambda_1 = \left[\frac{\|m\|_\infty}{\Gamma_q\left(\frac{13}{4}\right)} + \frac{\|m_0\|_\infty}{3} + \frac{2\|m\|_\infty}{3\Gamma_q\left(\frac{13}{4}\right)} \right.$$

$$\Lambda_2 = \left[\frac{\|m\|_\infty}{\Gamma_q\left(\frac{9}{4}\right)} + \frac{2\Gamma_q\left(\frac{4}{3}\right)\|m\|_\infty}{\Gamma_q\left(\frac{31}{12}\right)} \right.$$

$$\Lambda_3 = \left[\frac{\|m\|_\infty}{\Gamma_q\left(\frac{5}{4}\right)} + \frac{\Gamma_q\left(\frac{4}{3}\right)\left(\|m_2\|_\infty\Gamma_q\left(\frac{19}{12}\right) + 2\|m\|_\infty\right)}{\Gamma_q\left(\frac{19}{12}\right)} \right].$$

Table 1 Some Numerical Results for Calculation of $\Gamma_q(x)$ with $q = \frac{1}{8}$ Which is Constant, for $x = 9.5, 65, 110, 780$ in Algorithm 2.

n	$x = 9.5$	$x = 65$	$x = 110$	$x = 780$
1	2.679786	4432.545834	1804225.634753	1.29090809480473E + 45
2	2.674552	4423.888518	1800701.756560	1.28838678993206E + 45
3	2.673899	4422.808467	1800262.132108	1.28807224237593E + 45
4	2.673818	4422.673494	1800207.192468	1.28803293353064E + 45
5	2.673808	4422.656623	1800200.325222	1.28802802007493E + 45
6	<u>2.673806</u>	4422.654514	1800199.466820	1.28802740589531E + 45
7	2.673806	4422.654250	1800199.359519	1.28802732912289E + 45
8	2.673806	4422.654217	1800199.346107	1.28802731952634E + 45
9	2.673806	4422.654213	1800199.344430	1.28802731832677E + 45
10	2.673806	4422.654213	1800199.344221	1.28802731817683E + 45
11	2.673806	<u>4422.654212</u>	1800199.344195	1.28802731815808E + 45
12	2.673806	4422.654212	<u>1800199.344191</u>	1.28802731815574E + 45
13	2.673806	4422.654212	1800199.344191	1.28802731815545E + 45
14	2.673806	4422.654212	1800199.344191	<u>1.28802731815541E + 45</u>
15	2.673806	4422.654212	1800199.344191	1.28802731815541E + 45
16	2.673806	4422.654212	1800199.344191	1.28802731815541E + 45
17	2.673806	4422.654212	1800199.344191	1.28802731815541E + 45
18	2.673806	4422.654212	1800199.344191	1.28802731815541E + 45
19	2.673806	4422.654212	1800199.344191	1.28802731815541E + 45

Table 2 Some Numerical Results for Calculation of $\Gamma_q(x)$ with $q = \frac{1}{8}, \frac{1}{2}, \frac{4}{5}, \frac{8}{9}$ for $x = 9.5$ of Algorithm 2.

n	$q = \frac{1}{8}$	$q = \frac{1}{2}$	$q = \frac{4}{5}$	$q = \frac{8}{9}$
1	2.679786	136.046206	79062.138227	6301918.338883
2	2.674552	119.081545	41793.335091	2528395.395827
3	2.673899	111.658224	26290.733638	1232715.590371
4	2.673818	108.178242	18589.881264	689176.848061
5	2.673808	106.492553	14278.326587	426538.394173
6	<u>2.673806</u>	105.662861	11650.586796	285518.687713
7	2.673806	105.251251	9946.3508930	203363.796571
⋮	⋮	⋮	⋮	⋮
26	2.673806	104.841780	5522.283831	25842.863721
27	2.673806	104.841780	5513.202433	25230.371788
28	2.673806	<u>104.841779</u>	5505.949683	24699.649904
29	2.673806	104.841779	5500.155385	24238.446645
⋮	⋮	⋮	⋮	⋮
106	2.673806	104.841779	5477.048235	20879.606269
107	2.673806	104.841779	<u>5477.048234</u>	20879.566792
108	2.673806	104.841779	5477.048234	20879.531702
⋮	⋮	⋮	⋮	⋮
118	2.673806	104.841779	5477.048234	20879.337427
119	2.673806	104.841779	5477.048234	20879.327822
120	2.673806	104.841779	5477.048234	<u>20879.319284</u>

Table 3 Some Numerical Results for Calculation of $\Gamma_q(x)$ with $q = \frac{1}{8}, \frac{1}{2}, \frac{4}{5}, \frac{8}{9}$ for $x = 110$ of Algorithm 2.

n	$q = \frac{1}{8}$	$q = \frac{1}{2}$	$q = \frac{4}{5}$	$q = \frac{8}{9}$
1	1804225.634753	2.43388915243820E + 32	1.10933564801075E + 75	2.3996994906237E + 102
2	1800701.756560	2.12965300838343E + 32	5.41355796236824E + 74	7.1431517307455E + 101
3	1800262.132108	1.99654969535946E + 32	3.19616462101800E + 74	2.6837217226512E + 101
4	1800207.192468	1.93415751737948E + 32	2.14884539802207E + 74	1.1944485864825E + 101
5	1800200.325222	1.90393630617042E + 32	1.58553847001434E + 74	6.0526350536381E + 100
6	1800199.466820	1.88906180377847E + 32	1.25302695267477E + 74	3.3987862057282E + 100
7	1800199.359519	1.88168265610746E + 32	1.04280391429109E + 74	2.0741306563269E + 100
8	1800199.346107	1.87800749466975E + 32	9.02841142168746E + 73	1.3555712905453E + 100
9	1800199.344430	1.87617350297573E + 32	8.05899312693661E + 73	9.38129101307050E + 99
10	1800199.344221	1.87525740263248E + 32	7.36673088857628E + 73	6.81335603265770E + 99
11	1800199.344195	1.87479957611817E + 32	6.86049299667128E + 73	5.15556440821410E + 99
12	<u>1800199.344191</u>	1.87457071874804E + 32	6.48333340557523E + 73	4.04051908444650E + 99
⋮	⋮	⋮	⋮	⋮
48	1800199.344191	<u>1.87434189862553E + 32</u>	5.18960499065178E + 73	6.66324790738213E + 98
⋮	⋮	⋮	⋮	⋮
90	1800199.344191	1.87434189862553E + 32	<u>5.18923469131315E + 73</u>	6.50025876524830E + 98
91	1800199.344191	1.87434189862553E + 32	5.18923468501255E + 73	6.50013085733126E + 98
92	1800199.344191	1.87434189862553E + 32	5.18923467997207E + 73	6.50001716364224E + 98
93	1800199.344191	1.87434189862553E + 32	5.18923467593968E + 73	6.49991610435300E + 98
⋮	⋮	⋮	⋮	⋮
118	1800199.344191	1.87434189862553E + 32	5.18923465987107E + 73	6.49915022957670E + 98
119	1800199.344191	1.87434189862553E + 32	5.18923465985889E + 73	6.49914550293450E + 98
120	1800199.344191	1.87434189862553E + 32	5.18923465984914E + 73	<u>6.49914130147782E + 98</u>

Table 4 Some Numerical Results of $\Gamma_q(\alpha)$ in Example 2.5 with Different Values of q by Algorithm 2.

n	$\alpha = \frac{3}{4}$	$\alpha = \frac{5}{4}$	$\alpha = \frac{4}{3}$	$\alpha = \frac{19}{12}$	$\alpha = \frac{9}{4}$	$\alpha = \frac{7}{3}$	$\alpha = \frac{31}{12}$	$\alpha = \frac{13}{4}$
$q = \frac{1}{3}$								
1	1.1174	0.9592	0.9559	0.9673	1.1055	1.1315	1.2199	1.5327
2	1.1311	0.9505	0.9448	0.9500	1.0747	1.0990	1.1824	1.4805
3	1.1356	0.9476	0.9411	0.9444	1.0647	1.0886	1.1703	1.4638
4	1.1371	0.9467	0.9400	0.9425	1.0615	1.0851	1.1664	1.4583
5	1.1376	0.9464	0.9396	0.9419	1.0604	1.0840	1.1651	1.4564
6	1.1377	0.9463	0.9394	0.9417	1.0600	1.0836	1.1646	1.4558
7	1.1378	0.9462	0.9394	0.9417	1.0599	1.0835	1.1645	1.4556
8	1.1378	0.9462	0.9394	0.9416	1.0599	1.0834	1.1644	1.4556
9	1.1378	0.9462	0.9394	0.9416	1.0598	1.0834	1.1644	1.4555
10	1.1378	0.9462	0.9394	0.9416	1.0598	1.0834	1.1644	1.4555
$q = \frac{1}{2}$								
1	1.1069	0.9743	0.9772	1.0122	1.2620	1.3087	1.4715	2.1039
2	1.1377	0.9526	0.9493	0.9662	1.1655	1.2049	1.3437	1.8906
3	1.1522	0.9426	0.9364	0.9453	1.1221	1.1583	1.2865	1.7960
4	1.1593	0.9378	0.9302	0.9353	1.1015	1.1362	1.2594	1.7514
5	1.1628	0.9355	0.9272	0.9303	1.0915	1.1254	1.2463	1.7297
6	1.1645	0.9343	0.9257	0.9279	1.0865	1.1201	1.2398	1.7190
7	1.1654	0.9337	0.9249	0.9267	1.0841	1.1175	1.2365	1.7137
8	1.1658	0.9334	0.9245	0.9261	1.0828	1.1161	1.2349	1.7111
9	1.1660	0.9333	0.9244	0.9258	1.0822	1.1155	1.2341	1.7098
10	1.1662	0.9332	0.9243	0.9257	1.0819	1.1152	1.2337	1.7091
$q = \frac{4}{5}$								
1	0.9665	1.1206	1.1787	1.4118	2.6441	2.8906	3.8168	8.5184
2	1.0284	1.0602	1.0963	1.2516	2.1063	2.2761	2.9085	6.0237
3	1.0710	1.0218	1.0443	1.1539	1.8020	1.9312	2.4107	4.7288
4	1.1018	0.9954	1.0091	1.0891	1.6109	1.7160	2.1053	3.9658
5	1.1248	0.9766	0.9840	1.0438	1.4826	1.5723	1.9040	3.4780
6	1.1421	0.9628	0.9657	1.0111	1.3927	1.4718	1.7646	3.1483
7	1.1555	0.9523	0.9519	0.9868	1.3275	1.3992	1.6647	2.9162
8	1.1659	0.9444	0.9414	0.9685	1.2793	1.3455	1.5913	2.7481
9	1.1740	0.9383	0.9334	0.9545	1.2429	1.3051	1.5363	2.6235
10	1.1803	0.9335	0.9271	0.9436	1.2151	1.2743	1.4945	2.5297

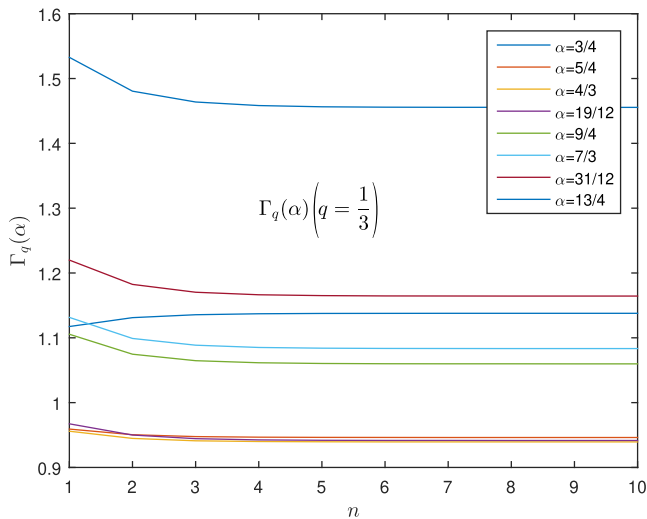


Fig. 1 Numerical results of $\Gamma_q(\alpha)$, where $q = \frac{1}{3}$ in Table 4.

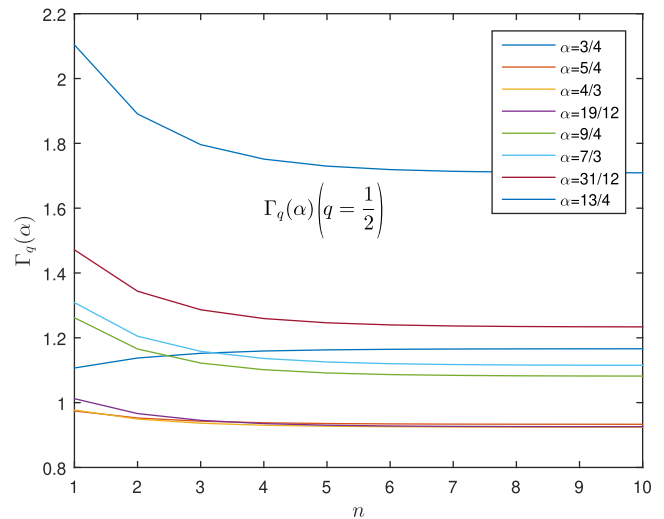


Fig. 2 Numerical results of $\Gamma_q(\alpha)$, where $q = \frac{1}{2}$ in Table 4.

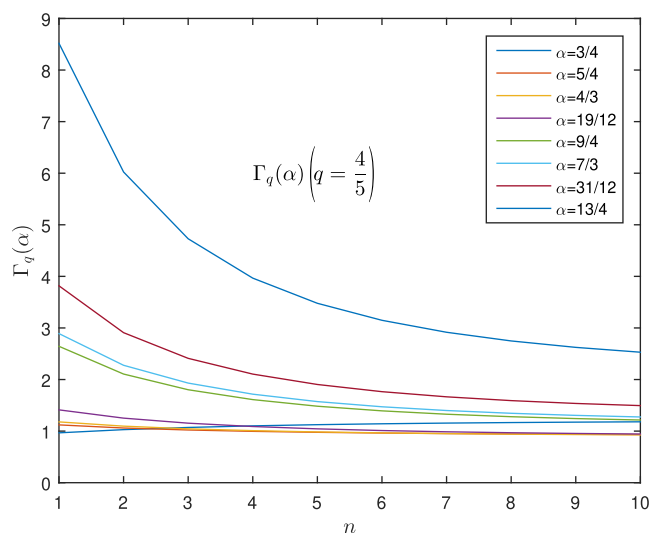


Fig. 3 Numerical results of $\Gamma_q(\alpha)$, where $q = \frac{4}{5}$ in Table 4.

Table 5 Some Numerical Results of Λ_1, Λ_2 and Λ_3 in Example 2.5 with Different Values of q .

n	Λ_1	Λ_2	Λ_3	$\frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3}$
$q = \frac{1}{3}$				
1	3.3364	1.1763	0.4559	0.2013
2	3.3955	1.1988	0.4592	0.1979
3	3.4147	1.2061	0.4602	0.1968
4	3.4219	1.2088	0.4606	0.1964
5	3.4240	1.2096	0.4608	0.1963
6	3.4244	1.2098	0.4608	0.1963
7	3.4246	1.2099	0.4608	0.1963
8	3.4251	1.2101	0.4608	0.1962
9	3.4251	1.2101	0.4608	0.1962
10	3.4251	1.2101	0.4608	0.1962
$q = \frac{1}{2}$				
1	2.9820	1.0480	0.4467	0.2234
2	3.1379	1.1076	0.4552	0.2127
3	3.2160	1.1375	0.4593	0.2078
4	3.2553	1.1525	0.4613	0.2054
5	3.2754	1.1601	0.4623	0.2042
6	3.2852	1.1639	0.4628	0.2036
7	3.2898	1.1656	0.4630	0.2033
8	3.2923	1.1666	0.4631	0.2032
9	3.2939	1.1671	0.4632	0.2031
10	3.2943	1.1673	0.4632	0.2031
$q = \frac{4}{5}$				
1	1.8371	0.6109	0.3881	0.3526
2	2.0805	0.7071	0.4077	0.3130
3	2.2800	0.7853	0.4216	0.2868
4	2.4430	0.8488	0.4319	0.2686
5	2.5751	0.9001	0.4395	0.2554
6	2.6823	0.9415	0.4454	0.2457
7	2.7686	0.9748	0.4499	0.2385
8	2.8380	1.0016	0.4534	0.2329
9	2.8943	1.0232	0.4562	0.2286
10	2.9392	1.0404	0.4584	0.2253

By checking the data in Tables 4 and 5, it is easy to check that

$$\begin{aligned}
 &H_d(T(t, u_1, u_2, u_3), F(t, v_1, v_2, v_3)) \\
 &\leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m(t)\theta \\
 &\times \left(\sum_{k=1}^3 |u_k - v_k| \right),
 \end{aligned}$$

and

$$\begin{aligned}
 &|f_j(t, u) - f_j(t, v)| \\
 &\leq \frac{1}{\Lambda_1 + \Lambda_2 + \Lambda_3} m_j(t)\psi(|u - v|),
 \end{aligned}$$

for $t \in J$ and $j = 0, 1, 2$. Since $\sup_{u \in N(0)} \|u\| = 0$, we have $\inf_{u \in C^2(J)} (\sup_{v \in N(u)} \|u - v\|) = 0$. Thus, N has the approximate endpoint property (please check Figs. 1–3). Now, by using Theorem 2.2, the fractional q -differential inclusion problem (2.9), (2.10) has at least one solution.

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