



Multiwave, multicomplexiton, and positive multicomplexiton solutions to a (3 + 1)-dimensional generalized breaking soliton equation



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Abstract There are a lot of physical phenomena which their mathematical models are decided by nonlinear evolution (NLE) equations. Our concern in the present work is to study a special type of NLE equations called the (3 + 1)-dimensional generalized breaking soliton (3D-GBS) equation. To this end, the linear superposition (LS) method along with a series of specific techniques are utilized and as an achievement, multiwave, multicomplexiton, and positive multicomplexiton solutions to the 3D-GBS equation are formally constructed. The study confirms the efficiency of the methods in handling a wide variety of nonlinear evolution equations.

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1. Introduction

During the last few decades, significant attention has been drawn to study nonlinear evolution equations especially their

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exact solutions. There are different types of exact solutions, for example, periodic solutions, soliton solutions, and so on. Many useful and well-organized techniques such as multiple exp-function method [1–3], simplified Hirota's method [4–8], Hirota's bilinear method [9–12], and linear superposition method [13–17] have been presented to handle NLE equations [18–37].

The linear superposition method which is an effective technique to extract multiwave solutions of nonlinear evolution

equations has received much attention among academic researchers. For example, Zhang et al. [15] utilized the LS method to derive the N -wave solution of a $(3 + 1)$ -dimensional generalized Kadomtsev–Petviashvili equation. The N -wave solution of the Hirota–Satsuma–Ito equation were obtained in [16] by Zhou and Manukure through the LS method. The LS method was adopted by Inc et al. [17] to look for the N -wave solution of the B-type Kadomtsev–Petviashvili equation [16,22,25,38–42].

In the present work, we deal with the following generalized $(3 + 1)$ -dimensional generalized breaking soliton equation [18]

$$\frac{\partial w}{\partial t} + \alpha \frac{\partial^3 u}{\partial x^3} + \beta \frac{\partial^3 u}{\partial y \partial x^2} + 6\alpha u \frac{\partial u}{\partial x} + 3\beta u \frac{\partial u}{\partial y} + 3\beta \frac{\partial u}{\partial x} v = 0,$$

$$\frac{\partial w}{\partial x} - \frac{\partial u}{\partial x} - \frac{\partial u}{\partial y} - \frac{\partial u}{\partial z} = 0,$$

$$\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} = 0,$$

or

$$\begin{aligned} \delta_x^{-1} \left(\frac{\partial^2 u}{\partial t \partial x} + \frac{\partial^2 u}{\partial t \partial y} + \frac{\partial^2 u}{\partial t \partial z} \right) + \alpha \frac{\partial^3 u}{\partial x^3} + \beta \frac{\partial^3 u}{\partial y \partial x^2} + 6\alpha u \frac{\partial u}{\partial x} \\ + 3\beta u \frac{\partial u}{\partial y} + 3\beta \frac{\partial u}{\partial x} \delta_x^{-1} \frac{\partial u}{\partial y} = 0, \end{aligned} \quad (1)$$

and extracting multiwave, multicomplexiton, and positive multicomplexiton solutions of it using the linear superposition method along with a series of specific techniques. The above 3D-GBS equation is a generalization of the following $(2 + 1)$ -dimensional generalized breaking soliton equation

$$\frac{\partial u}{\partial t} + \alpha \frac{\partial^3 u}{\partial x^3} + \beta \frac{\partial^3 u}{\partial y \partial x^2} + 6\alpha u \frac{\partial u}{\partial x} + 3\beta u \frac{\partial u}{\partial y} + 3\beta \frac{\partial u}{\partial x} v = 0,$$

$$\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} = 0,$$

which has been studied via different techniques such as ansatz methods [19] and Hirota's bilinear method [20].

Gai et al. in [18] by considering the transformation

$$u = 2(\ln \varphi)_{xx}, v = 2(\ln \varphi)_{xy},$$

and utilizing the symbolic computations provided the Hirota's bilinear form of the 3D-GBS Eq. (1) as follows

$$\begin{aligned} HBF_{3D-GBS} \equiv & (\mathcal{D}_x \mathcal{D}_t + \mathcal{D}_y \mathcal{D}_t + \mathcal{D}_z \mathcal{D}_t + \alpha \mathcal{D}_x^4 + \beta \mathcal{D}_x^3 \mathcal{D}_y) \varphi \cdot \varphi \\ = & 0, \end{aligned} \quad (2)$$

which $\mathcal{D}_x^4, \mathcal{D}_x^3 \mathcal{D}_y, \mathcal{D}_x \mathcal{D}_t, \mathcal{D}_y \mathcal{D}_t$, and $\mathcal{D}_z \mathcal{D}_t$ are the Hirota's operators. Gai and his collaborators [18] found different wave structures of the 3D-GBS equation such as lump-type solutions, rogue wave type solutions, breather lump wave solutions, and interaction solutions. Owing to the exact solutions reported in [18], the current paper presents multiwave, multicomplexiton, and positive multicomplexiton solutions of the

3D-GBS equation by means of the linear superposition method along with a series of specific techniques.

2. 3D-GBS equation and its multiwave, multicomplexiton, and positive multicomplexiton solutions

In the current section, multiwave, multicomplexiton, and positive multicomplexiton solutions of the 3D-GBS equation are formally acquired. The dynamic and evolution behaviors for a positive complexiton solution are demonstrated by portraying its three dimensional and density plots.

2.1. Multiwave solution

To construct the multiwave solution to the 3D-GBS equation, we seek $a_j, j = 1, 2, 3, 4$ and $\tau_j, j = 1, 2, 3, 4$ such that [15]

$$\begin{aligned} & \alpha a_1^4 (x^{\tau_1} - y^{\tau_1})^4 + \beta a_1^3 a_2 (x^{\tau_1} - y^{\tau_1})^3 (x^{\tau_2} - y^{\tau_2}) \\ & + a_1 a_4 (x^{\tau_1} - y^{\tau_1}) (x^{\tau_4} - y^{\tau_4}) + a_2 a_4 (x^{\tau_2} - y^{\tau_2}) (x^{\tau_4} - y^{\tau_4}) \\ & + a_3 a_4 (x^{\tau_3} - y^{\tau_3}) (x^{\tau_4} - y^{\tau_4}) \\ = & 0. \end{aligned} \quad (3)$$

By simple analysis, one obtains $a_j, j = 1, 2, 3, 4$ if $(\tau_1, \tau_2, \tau_3, \tau_4)$ be considered as $(1, 1, 1, 3)$. After substituting $\tau_j, j = 1, 2, 3, 4$ into Eq. (3) and equating the coefficients of the resulting expression to zero, one arrives at

$$\alpha a_1^4 + \beta a_1^3 a_2 + a_1 a_4 + a_2 a_4 + a_3 a_4 = 0,$$

$$4\alpha a_1^4 + 4\beta a_1^3 a_2 + a_1 a_4 + a_2 a_4 + a_3 a_4 = 0,$$

$$6\alpha a_1^4 + 6\beta a_1^3 a_2 = 0.$$

The nontrivial solution of the above nonlinear algebraic set is

$$a_2 = -\frac{\alpha}{\beta} a_1, a_3 = \frac{(\alpha - \beta)}{\beta} a_1.$$

Now, by assuming $a_1 = 1$, the following multiwave solution to the 3D-GBS equation is derived

$$u = 2(\ln \varphi)_{xx}, v = 2(\ln \varphi)_{xy},$$

in which

$$\varphi = \sum_{j=1}^N c_j e^{\theta_j}, \theta_j = k_j x - \frac{\alpha}{\beta} k_j y + \frac{(\alpha - \beta)}{\beta} k_j z + a_4 k_j^3 t.$$

2.2. Multicomplexiton solution

Now to acquire the multicomplexiton solution of the 3D-GBS equation, let us consider [16]

$$k_j = k_{1j} + ik_{2j}, j = 1, \dots, N, \quad i^2 = -1,$$

which k_{1j} and $k_{2j}(j = 1, \dots, N)$ are real parameters. Such an assumption results in

$$\begin{aligned}\theta_j &= k_j x - \frac{\alpha}{\beta} k_j y + \frac{(\alpha - \beta)}{\beta} k_j z + a_4 k_j^3 t = \theta_{j,1} + i\theta_{j,2}, \bar{\theta}_j \\ &= \bar{k}_j x - \frac{\alpha}{\beta} \bar{k}_j y + \frac{(\alpha - \beta)}{\beta} \bar{k}_j z + a_4 \bar{k}_j^3 t = \theta_{j,1} - i\theta_{j,2}.\end{aligned}$$

It is clear that e^{θ_j} and $e^{\bar{\theta}_j}$ satisfy the bilinear form (2). Therefore, owing to the linear superposition principle, the new expression

$$\begin{aligned}\varphi &= \sum_{j=1}^N \left(c_j e^{\theta_j} + \bar{c}_j e^{\bar{\theta}_j} \right) \\ &= \sum_{j=1}^N e^{\theta_{j,1}} (c_{j,1} \cos(\theta_{j,2}) + c_{j,2} \sin(\theta_{j,2})), c_{j,1}, c_{j,2} \in \mathbb{R},\end{aligned}$$

is also a nontrivial solution of the bilinear form of the 3D-GBS equation. Finally, the multicomplexiton solution to the 3D-GBS equation can be written as

$$u = 2(\ln \varphi)_{xx}, v = 2(\ln \varphi)_{xy},$$

in which

$$\varphi = \sum_{j=1}^N e^{\theta_{j,1}} (c_{j,1} \cos(\theta_{j,2}) + c_{j,2} \sin(\theta_{j,2})).$$

As a special case, suppose that $N = 2$, $k_1 = 1 + i$, and $k_2 = -1 - i$, then

$$\begin{aligned}\theta_1 &= x - \frac{\alpha}{\beta} y + \frac{(\alpha - \beta)}{\beta} z - 2a_4 t \\ &\quad + i \left(x - \frac{\alpha}{\beta} y + \frac{(\alpha - \beta)}{\beta} z + 2a_4 t \right) \\ &= \theta_{1,1} + i\theta_{1,2}, \\ \theta_2 &= -x + \frac{\alpha}{\beta} y - \frac{(\alpha - \beta)}{\beta} z + 2a_4 t \\ &\quad + i \left(-x + \frac{\alpha}{\beta} y - \frac{(\alpha - \beta)}{\beta} z - 2a_4 t \right) \\ &= \theta_{2,1} - i\theta_{2,2}.\end{aligned}$$

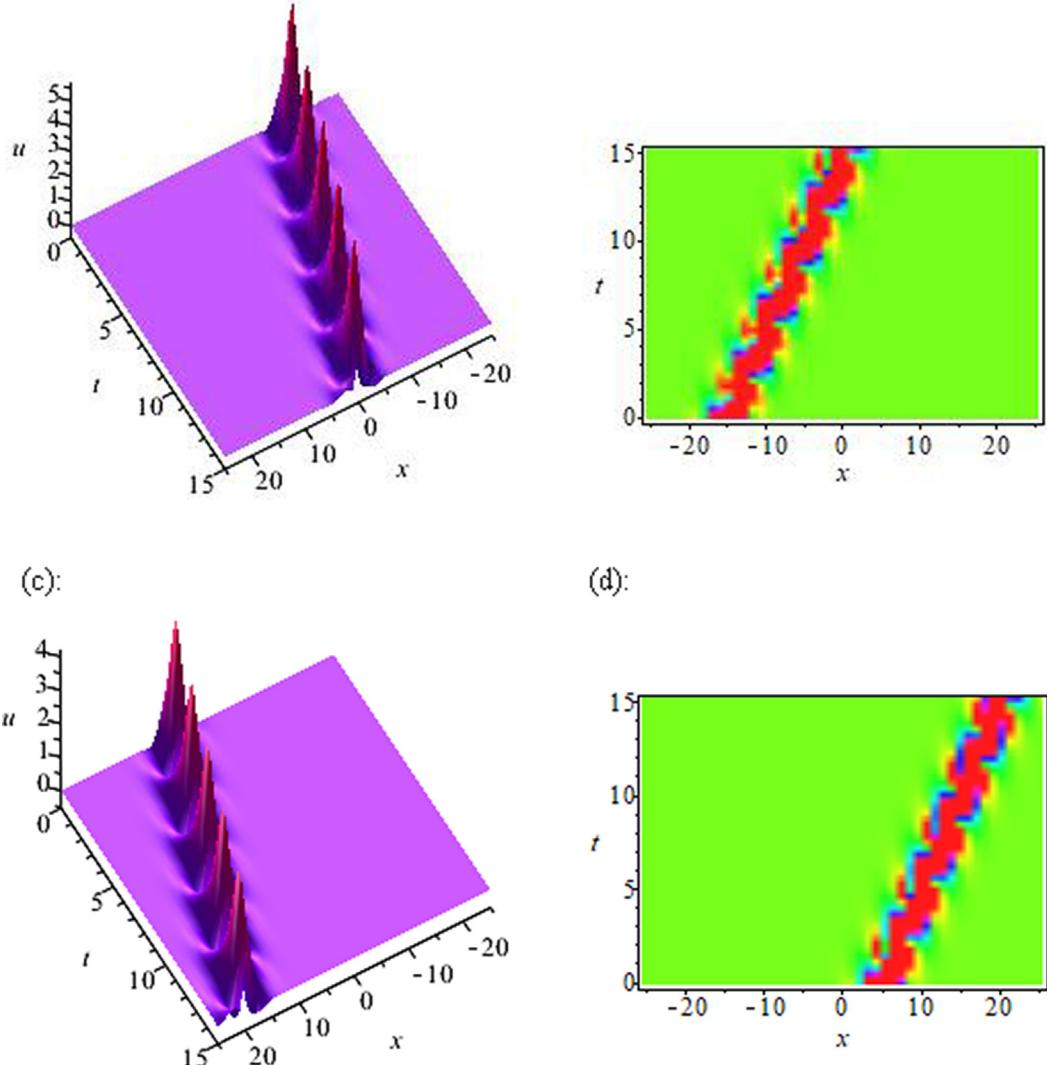


Fig. 1 The function u when $y = z = -15$: (a) Three-dimensional plot and (b) density plot; The function u when $y = z = 5$: (c) Three-dimensional plot and (d) density plot.

Now, the complexiton solution of the 3D-GBS equation is
 $u = 2(\ln \varphi)_{xx}, v = 2(\ln \varphi)_{xy}$,

in which

$$\begin{aligned} \varphi = & e^{x-\frac{\alpha}{\beta}y+\frac{(\alpha-\beta)}{\beta}z-2a_4t} \left(c_{1,1} \cos \left(x - \frac{\alpha}{\beta}y + \frac{(\alpha-\beta)}{\beta}z + 2a_4t \right) \right. \\ & + c_{1,2} \sin \left(x - \frac{\alpha}{\beta}y + \frac{(\alpha-\beta)}{\beta}z + 2a_4t \right) \left. \right) \\ & + e^{-x+\frac{\alpha}{\beta}y-\frac{(\alpha-\beta)}{\beta}z+2a_4t} \left(c_{2,1} \cos \left(-x + \frac{\alpha}{\beta}y - \frac{(\alpha-\beta)}{\beta}z - 2a_4t \right) \right. \\ & + c_{2,2} \sin \left(-x + \frac{\alpha}{\beta}y - \frac{(\alpha-\beta)}{\beta}z - 2a_4t \right) \left. \right). \end{aligned}$$

$$u = -2 \frac{4 \sinh(-x-y+2z+t) \sin(x+y-2z+t) - 3}{4 \cosh(-x-y+2z+t)^2 + 4 \cosh(-x-y+2z+t) \cos(x+y-2z+t) + \cos(x+y-2z+t)^2},$$

2.3. Positive multicomplexiton solution

In a manner similar to that accomplished in [16], one can establish the following positive multicomplexiton solution to the 3D-GBS equation

$$u = 2(\ln \varphi)_{xx}, v = 2(\ln \varphi)_{xy},$$

in which

$$\begin{aligned} \varphi = & \sum_{j=1}^N c_j \cosh \left(k_j x - \frac{\alpha}{\beta} k_j y + \frac{(\alpha-\beta)}{\beta} k_j z + a_4 k_j^3 t \right) \\ & + \sum_{j=N+1}^{N+M} c_j \cos \left(k_j x - \frac{\alpha}{\beta} k_j y + \frac{(\alpha-\beta)}{\beta} k_j z - a_4 k_j^3 t \right), c_j \in \mathbb{R}. \end{aligned}$$

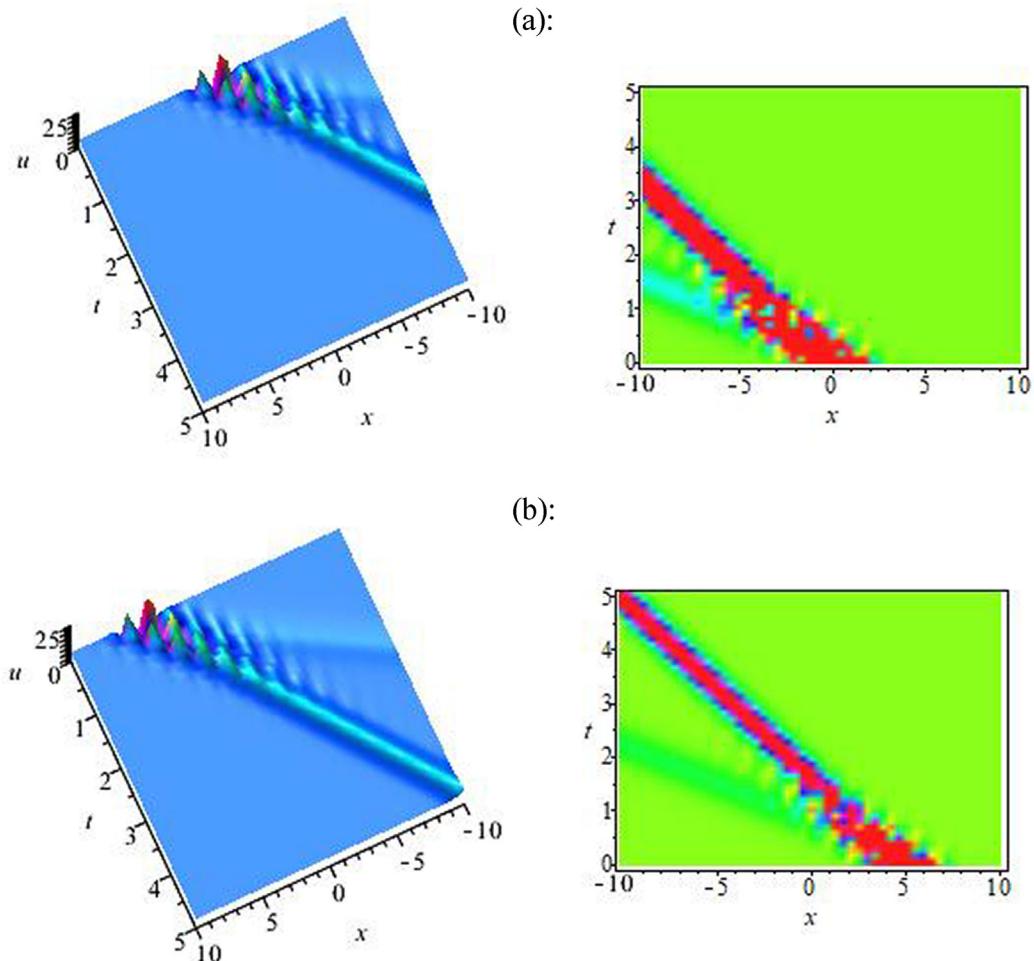


Fig. 2 The function u for $M = N = 2$, $c_1 = 1$, $c_2 = 1.8$, $c_3 = 1$, $c_4 = 1.5$, $k_1 = 1$, $k_2 = 2$, $k_3 = 3$, $k_4 = 4$, $a_4 = 1$, $\alpha = -1$, $\beta = 1$, when (a) $y = z = 0$ and (b) $y = z = 5$.

$$v = -2 \frac{4 \sinh(-x - y + 2z + t) \sin(x + y - 2z + t) - 3}{4 \cosh(-x - y + 2z + t)^2 + 4 \cosh(-x - y + 2z + t) \cos(x + y - 2z + t) + \cos(x + y - 2z + t)^2}.$$

It should be mentioned that if $c_j > 0$ for $j = 1, 2, \dots, N$ and $\sum_{j=1}^N c_j > \sum_{j=N+1}^{N+M} |c_j|$, then the function φ is a positive function. For example, when $M = N = 1$, $c_1 = 2$, $c_2 = 1$, $k_1 = 1$, $k_2 = -1$, $a_4 = -1$, $\alpha = -1$, and $\beta = 1$, we find the following positive complexiton solution

The dynamical and evolutionary behaviors for the above positive complexiton solution have been demonstrated by portraying its three dimensional and density plots in Fig. 1.

Fig. 2 shows three dimensional and density plots of the positive complexiton solution for $M = N = 2$, $c_1 = 1$, $c_2 = 1.8$,

$c_3 = 1$, $c_4 = 1.5$, $k_1 = 1$, $k_2 = 2$, $k_3 = 3$, $k_4 = 4$, $a_4 = 1$, $\alpha = -1$, $\beta = 1$, when (a) $y = z = 0$ and (b) $y = z = 5$.

2.4. Other soliton and periodic solutions

Other soliton solutions of the 3D-GBS equation are extracted by considering the following hyperbolic functions [21,22]

$$u(x, y, z, t) = A_0 + A_1 \tanh(k_1 x + l_1 y + m_1 z + w_1 t),$$

$$v(x, y, z, t) = \frac{l_1}{k_1} (A_0 + A_1 \tanh(k_1 x + l_1 y + m_1 z + w_1 t)), \quad (4)$$

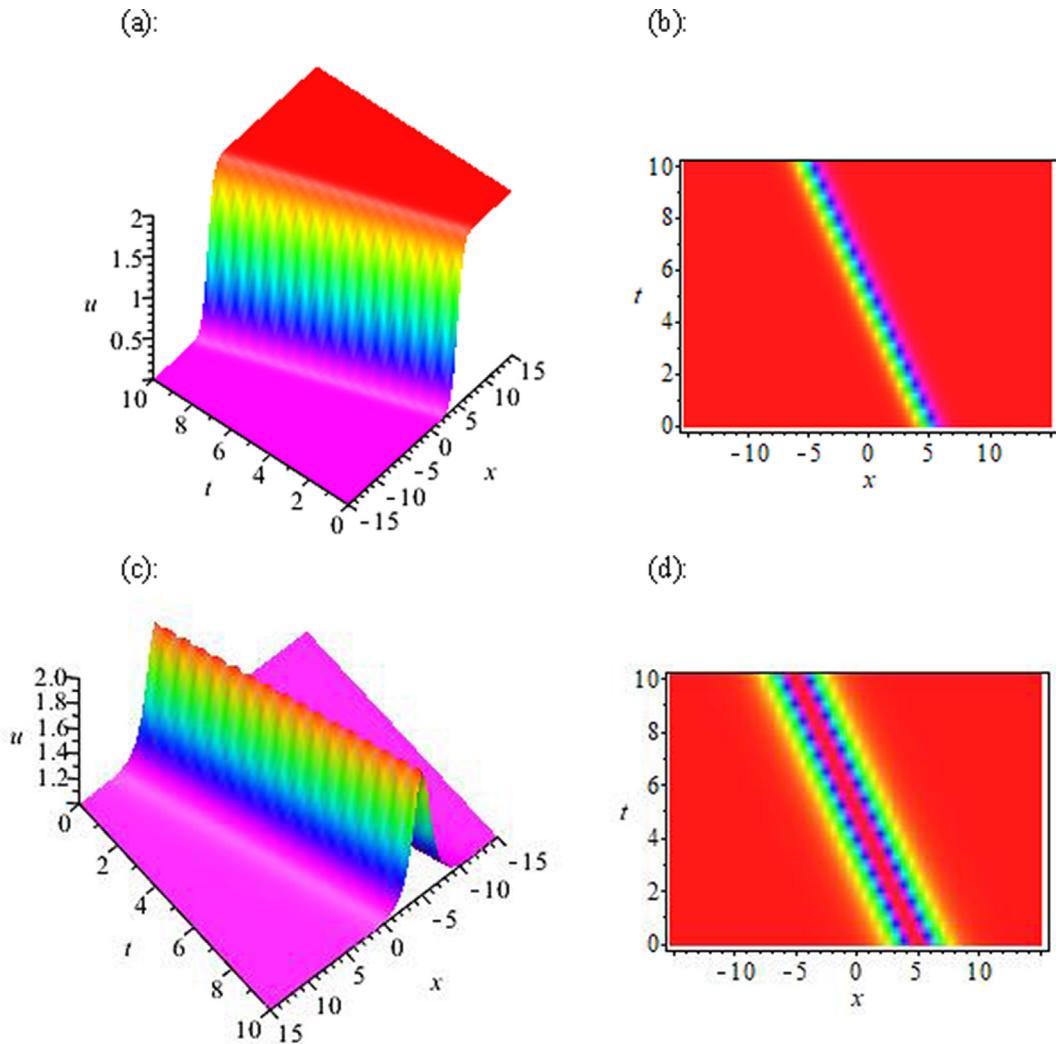


Fig. 3 The hyperbolic tangent function u when $A_0 = 1$, $A_1 = 1$, $k_1 = 1$, $w_1 = 1$, $\alpha = -1$, $\beta = 1$, and $y = z = 5$: (a) Three-dimensional plot and (b) density plot; The hyperbolic secant function u when $A_0 = 1$, $A_1 = 1$, $k_1 = 1$, $w_1 = 1$, $\alpha = -1$, $\beta = 1$, and $y = z = 5$: (c) Three-dimensional plot and (d) density plot.

and

$$u(x, y, z, t) = A_0 + A_1 \operatorname{sech}(k_1 x + l_1 y + m_1 z + w_1 t),$$

$$v(x, y, z, t) = \frac{l_1}{k_1} (A_0 + A_1 \operatorname{sech}(k_1 x + l_1 y + m_1 z + w_1 t)). \quad (5)$$

Setting the solutions (4) and (5) in the 3D-GBS equation and solving the resulting system yields the following solution

$$l_1 = -\frac{\alpha}{\beta} k_1, m_1 = \frac{(\alpha - \beta)}{\beta} k_1.$$

Now, the following soliton solutions to the 3D-GBS equation can be obtained

$$u(x, y, z, t) = A_0 + A_1 \tanh \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right),$$

$$v(x, y, z, t) = -\frac{\alpha}{\beta} \left(A_0 + A_1 \tanh \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right) \right),$$

and

$$u(x, y, z, t) = A_0 + A_1 \operatorname{sech} \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right),$$

$$v(x, y, z, t) = -\frac{\alpha}{\beta} \left(A_0 + A_1 \operatorname{sech} \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right) \right).$$

Similarly, the following soliton solutions can be derived

$$u(x, y, z, t) = A_0 + A_1 \coth \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right),$$

$$v(x, y, z, t) = -\frac{\alpha}{\beta} \left(A_0 + A_1 \coth \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right) \right),$$

and

$$u(x, y, z, t) = A_0 + A_1 \operatorname{csch} \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right),$$

$$v(x, y, z, t) = -\frac{\alpha}{\beta} \left(A_0 + A_1 \operatorname{csch} \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right) \right).$$

The dynamical and evolutionary behaviors for a series of the obtained soliton solutions have been shown by representing their three dimensional and density plots in Fig. 3.

It is evident that Fig. 3(a) shows a kink-type soliton solution whereas Fig. 3(c) demonstrates a bright soliton solution.

Finally, the following preiodic solutions to the 3D-GBS equation can be gained

$$u(x, y, z, t) = A_0 + A_1 \tan \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right),$$

$$v(x, y, z, t) = -\frac{\alpha}{\beta} \left(A_0 + A_1 \tan \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right) \right),$$

and

$$u(x, y, z, t) = A_0 + A_1 \cot \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right),$$

$$v(x, y, z, t) = -\frac{\alpha}{\beta} \left(A_0 + A_1 \cot \left(k_1 x - \frac{\alpha}{\beta} k_1 y + \frac{(\alpha - \beta)}{\beta} k_1 z + w_1 t \right) \right).$$

3. Conclusion

A (3 + 1)-dimensional generalized breaking soliton equation with diverse applications in physical sciences was considered in the present study. Through the bilinear form of the (3 + 1)-dimensional generalized breaking soliton equation and the linear superposition principle along with a series of specific techniques, distinct exact solutions including multiwave, multicomplexiton, and positive multicomplexiton solutions to the 3D-GBS equation were formally extracted. The results of the present work confirmed the efficiency of the schemes in handling a wide variety of nonlinear evolution equations.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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