http://www.aimspress.com/journal/Math

Research article

# Analysis of positive measure reducibility for quasi-periodic linear systems under Brjuno-Rüssmann condition 

Muhammad Afzal ${ }^{1}$, Tariq Ismaeel $^{2}$, Riaz Ahmad ${ }^{3, *}$, Ilyas Khan ${ }^{4, *}$ and Dumitru Baleanu ${ }^{56,7}$<br>${ }^{1}$ Department of Mathematics, Division of Science and Technology, University of Education, Lahore 54770, Pakistan<br>${ }^{2}$ Department of Mathematics, Government College University, Lahore 54000, Pakistan<br>${ }^{3}$ Faculty of Science, Yibin University, Yibin 644000, China<br>${ }^{4}$ Department of Mathematics, College of Science Al-Zulfi, Majmaah University, Al-Majmaah, P.O. Box 66, Majmaah 11952, Saudi Arabia<br>${ }^{5}$ Department of Mathematics, Cankaya University, Ankara 06790, Turkey<br>${ }^{6}$ Institute of Space Sciences, 077125 Magurele, Romania<br>${ }^{7}$ Department of Medical Research, China Medical University Hospital, China Medical University, Taichung 40447, Taiwan

* Correspondence: Email: riazgill2007@gmail.com, i.said@mu.edu.sa.

$$
\begin{aligned}
& \text { Abstract: In this article, we discuss the positive measure reducibility for quasi-periodic linear systems } \\
& \text { close to a constant which is defined as: } \\
& \qquad \frac{d x}{d t}=(A(\lambda)+Q(\varphi, \lambda)) x, \dot{\varphi}=\omega, \\
& \text { where } \omega \text { is a Brjuno vector and parameter } \lambda \in(a, b) \text {. The result is proved by using the KAM method, } \\
& \text { Brjuno-Rüssmann condition, and non-degeneracy condition. }
\end{aligned}
$$

Keywords: quasi-periodic; Brjuno-Rüssmann condition; reducibility; KAM method
Mathematics Subject Classification: 37K55, 70K40

## 1. Introduction

Suppose the quasi-periodic linear system

$$
\begin{equation*}
\frac{d x}{d t}=A\left(\omega_{1} t, \omega_{2} t, \ldots, \omega_{r} t\right) x \tag{1.1}
\end{equation*}
$$

in which $t \in \mathbb{R}, x \in \mathbb{C}^{r}, A\left(\omega_{1} t, \omega_{2} t, \ldots, \omega_{r} t\right)$ is quasi-periodic(q-p) time dependent $r \times r$ matrix and the basic frequencies $\omega_{1}, \ldots, \omega_{r}$ are rational independent.

The system (1.1) is said to be reducible, if there exists a so called quasi-periodic Lyapunov-Perron (L-P) transformation $x=P\left(\omega_{1} t, \ldots, \omega_{r} t\right) y$, so that the transformed system is a linear system with constant coefficients. We call the transformation $x=P\left(\omega_{1} t, \ldots, \omega_{r} t\right) y$ is quasi-periodic L-P transformation, if $P(t)$ is non singular and $P, P^{-1}$ and $\dot{P}$ are quasi-periodic and are bounded in $t \in \mathbb{R}$.

Many researchers have discussed the reducibility problems for quasi-periodic linear systems. For $r=1$, i.e., the periodic case, the well known Floquet theorem states that there always exists a periodic change of variables $x=P\left(\omega_{1} t\right) y$ so that the system $\dot{x}=A\left(\omega_{1} t\right) x$ is reducible to a constant coefficient system $\dot{y}=B y, \dot{\varphi}=\omega$, where $B$ is a constant matrix. For $r>1$, i.e., quasi-periodic case, there is an example in [1] which shows that the system (1.1) is not always reducible. Earlier for q-p case, Coppel [2] proved that a linear differential equation with bounded coefficient matrix is pseudo-autonomous if and only if it is almost reducible and Johnson and Sell [3] showed that if (1.1) satisfies the full spectrum assumption, then there is a quasi-periodic linear change of variables $x=P\left(\omega_{1} t, \ldots, \omega_{r} t\right) y$ that transforms (1.1) to a constant coefficient system $\dot{y}=B y$, where $B$ is a constant matrix. Their results failed for the pure imaginary spectrum [4].

The first reducibility result by KAM method was given by Dinaburg and Sinai [5] who proved that the linear Schrödinger equation $\frac{d^{2} x}{d t^{2}}+q\left(\omega_{1} t, \omega_{2} t, \ldots, \omega_{r} t\right) x=\lambda x$ is reducible for 'most' large enough $\lambda$ in measure sense, where $\omega$ is fixed satisfying the Diophantine condition: $|\langle k, \omega\rangle|>\frac{\alpha^{-1}}{\left.|k|\right|^{r}}, 0 \neq k \in \mathbb{Z}^{r}$, where $\alpha, \tau$ are positive constants. See also Rüssmann [6] for a refined result.

In 1992 Jorba and Simó [7] considered the following linear differential system

$$
\begin{equation*}
\frac{d x}{d t}=\left(A+\lambda \bar{Q}+\lambda^{2} Q\left(\omega_{1} t, \ldots, \omega_{r} t\right)\right) x, \quad x \in \mathbb{R}^{d} \tag{1.2}
\end{equation*}
$$

in which $A, \bar{Q}$ are constant diagonal matrices, and $Q$ is an analytic q-p matrix having $r$ basic frequencies, and with a small parameter $\lambda$. Using the KAM method, They proved that there exists a positive measure Cantor subset $E \subset\left(0, \lambda_{0}\right), \lambda_{0} \ll 1$ such that for any $\lambda \in E$, the system (1.2) is reducible, provided that the following non-degeneracy conditions

$$
\begin{equation*}
\left|\alpha_{i}(\lambda)-\alpha_{j}(\lambda)\right|>\delta>0, \quad\left|\frac{d}{d \lambda}\left(\alpha_{i}(\lambda)-\alpha_{j}(\lambda)\right)\right|>\chi>0, \quad \forall 1 \leq i<j \leq d \tag{1.3}
\end{equation*}
$$

where $\alpha_{i}(\lambda), 1 \leq i \leq m$, are the eigenvalues of $\bar{A}=A+\lambda \bar{Q}$. In 1999, Xu [8] improved the result for the weaker non-degeneracy conditions.

Eliasson [9] considered the following linear Shrödinger equation

$$
\frac{d^{2} x}{d t^{2}}+(\lambda+Q(\omega t) x=0
$$

For almost all $\lambda \in(a, b)$, the full measure reducibility result is proved in a Lebesgue measure sense provided that $Q$ is small. On the other hand, Krikorian [10] generalized the work for linear systems with coefficients in $s o(3)$. Then, Eliasson [11] discussed the full measure reducibility result for the following parameter dependent systems

$$
\begin{equation*}
\frac{d x}{d t}=\left(A(\lambda)+Q\left(\omega_{1} t, \ldots, \omega_{r} t, \lambda\right)\right) x \tag{1.4}
\end{equation*}
$$

in which $t \in \mathbb{R}, x \in \mathbb{C}^{d}$, a constant matrix $A$ of dimension $d \times d$, the parameter $\lambda \in(a, b)$, and an analytic mapping $Q: T^{r} \times(a, b) \rightarrow g l(m, \mathbb{C})$, a Diophantine vector $\left(\omega_{1}, \ldots, \omega_{r}\right)$ and for sufficiently small $|Q|$.

He and You [12] proved the positive measure reducibility result for the following quasi-periodic skew-product systems: $\frac{d x}{d t}=(A(\lambda)+Q(\varphi, \lambda)) x, \dot{\varphi}=\omega$, close to constant. The result is proved by using KAM method, under weaker non-resonant conditions and non-degeneracy conditions.

All the above mentioned results only discuss the reducibility of linear systems with the Diophantine condition

$$
\begin{equation*}
|\langle k, \omega\rangle| \geq \frac{\alpha^{-1}}{|k|^{\tau}}, \quad 0 \neq k \in \mathbb{Z}^{d} \tag{1.5}
\end{equation*}
$$

where $\alpha>1$ and $\tau>d-1$.
In our problem, we are going to focussed on the Brjuno-Rüssmann condition (see [13, 14]) which is slightly weaker than the Diophantine condition (1.5), if the frequencies $\omega=\left(\omega_{1}, \ldots, \omega_{d}\right)$ satisfy

$$
\begin{equation*}
|\langle k, \omega\rangle| \geq \frac{\alpha^{-1}}{\Delta(|k|)}, \quad 0 \neq k \in \mathbb{Z}^{d} \tag{1.6}
\end{equation*}
$$

where $\alpha>1$ and some Rüssmann approximation function $\Delta$. These are continuous, increasing and unbounded functions $\Delta:[0,+\infty) \rightarrow[1,+\infty)$ such that $\Delta(0)=1$ and

$$
\int_{1}^{+\infty} \frac{\ln \Delta(t)}{t^{2}} d t<\infty .
$$

Remark: If we have $\Delta(t)=t^{\tau}$, then the Brjuno-Rüssmann conditions (1.6) becomes the Diophantine conditions (1.5).

Furthermore, in this article we will generalize the result of He and You [12] for quasi-periodic linear systems using Brjuno-Rüssmann non-resonant condition which is slightly weaker than the Diophantine condition.

This article is organized as: at the end of Section 1, the statement of the main result is given and in Section 2 proof of the main result is given.

To state our main result, we now give some definitions and results.
Definition 1.1. ( $[15,16])$
A vector $\omega \in \mathbb{R}^{d}$ is Brjuno if the following condition is satisfied

$$
\sum_{n=1}^{\infty} 2^{-n} \ln \left(\frac{1}{\Omega_{n}}\right)<\infty, \quad \Omega_{n}=\min _{v \in \mathbb{Z}^{d}, 0<|v| \leq 2^{n}}|\langle\omega, v\rangle| .
$$

The set of Brjuno vectors is of full Lebesgue measure. In particular, it contains all Diophantine vectors. Conversely, there are vectors that are Brjuno and are not Diophantine.

This article aims to discuss the positive measure reducibility for q-p linear systems like (1.4) proposed by He and You [12]. The existed positive measure reducibility is discussed by using the Diophantine conditions, but we will discuss the positive measure reducibility using the Brjuno-Rüssmann condition.

Equivalently, for the system (1.4), we suppose the following skew-product system

$$
\begin{equation*}
\frac{d x}{d t}=(A(\lambda)+Q(\varphi, \lambda)) x, \quad \dot{\varphi}=\omega, \tag{1.7}
\end{equation*}
$$

where $x \in \mathbb{C}^{r}$, the parameter $\lambda \in \Lambda=(a, b), A$ is a $r \times r$ constant matrix, and $Q(\varphi, \lambda)$ is an analytic mapping from $\mathbb{T}^{r} \times(a, b)$ to $g l(m, \mathbb{C}),\left(\omega_{1}, \omega_{2}, \cdots, \omega_{n}\right)$ is a Brjuno vector and $|Q|$ is sufficiently small.

In our discussion, we will use the following equivalent formulation of reducibility:
Consider

$$
\begin{equation*}
\frac{d Z}{d t}=b(t) Z \tag{1.8}
\end{equation*}
$$

be an analytic q-p linear system. For the skew-product system, it can be rewritten as:

$$
\begin{equation*}
\frac{d Z}{d t}=B(\varphi) Z, \quad \dot{\varphi}=\omega \tag{1.9}
\end{equation*}
$$

where $b, B$ are in the Lie algebra $g=g(m, \mathbb{C})$ and their solutions have values in the Lie group $G=$ $G L(m, \mathbb{C})$. For a complex neighbourhood $W_{h}\left(\mathbb{T}^{r}\right)$ if $B$ is an analytic on $W_{h}\left(\mathbb{T}^{r}\right)$, then we represent $B \in C_{h}^{\omega}\left(\mathbb{T}^{r}, g\right)$. It is said that the analytic g-valued functions $B_{1}, B_{2} \in C_{h}^{\omega}\left(\mathbb{T}^{r}, g\right)$ are conjugated, if $\exists$ a L-P transformation G-valued function $P \in C_{h}^{\omega}\left(\mathbb{T}^{r}, G\right)$, s.t. for the solutions $Z_{1}, Z_{2}$ corresponding to $B_{1}, B_{2}$, we have the following relation

$$
Z_{2}=P(\varphi) Z_{1}
$$

and the conjugate relation can be denoted by:

$$
B_{1} \equiv B_{2}(\bmod P) .
$$

It is easy to prove that $B_{1} \equiv B_{2}(\bmod P)$ can equivalently be written in the form of following equality

$$
\begin{equation*}
B_{2}=D_{\omega} P \cdot P^{-1}+P B_{1} P^{-1}, \tag{1.10}
\end{equation*}
$$

where $D_{\omega}=\frac{\partial}{\partial \varphi} \cdot \dot{\varphi}$ denotes the derivative in the direction of frequency vector $\omega . B_{1}$ is known to be reducible if it conjugates to a constant $B_{2}$.

In our article, we shall prove that, for any $\lambda \in \Lambda=(a, b)$, where $\lambda$ is the parameter and $\Lambda$ is a positive measure set,then $\exists$ a L-P transformation $P(\varphi)$, such that the system $A+Q(\varphi)$ is transformed into a constant system $A^{*}$.

For the positive measure reducibility, we will use the non-degeneracy conditions (or the transverse conditions as in Eliasson and Krikorian terminology) . Without loss of generality, let's suppose a block-diagonal matrix $A(\lambda)=\operatorname{diag}\left(A_{1}(\lambda), \cdots, A_{s}(\lambda)\right)$ with

$$
\operatorname{dist}\left(\sigma\left(A_{i}\right), \sigma\left(A_{j}\right)\right)>\varrho>0, \text { for } i \neq j
$$

where $\sigma\left(A_{i}\right)$ represents the eigenvalues set for $A_{i}$. Let (see in [12] for definition)

$$
\begin{gathered}
J_{i j}(k, \lambda)=i\langle k, \omega\rangle I_{l_{i} l_{j}}+\left(I_{l_{i}} \otimes A_{j}(\lambda)-A_{i}^{T}(\lambda) \otimes I_{l_{j}}\right), \\
J(k, \lambda)=i\langle k, \omega\rangle I_{n^{2}}+\left(I_{n} \otimes A(\lambda)-A^{T}(\lambda) \otimes I_{n}\right), \\
d_{i j}(k, \lambda)=\operatorname{det}\left[\left\langle\langle k, \omega\rangle I_{l_{i} l_{j}}+\left(I_{l_{i}} \otimes A_{j}(\lambda)-A_{i}^{T}(\lambda) \otimes I_{l_{j}}\right)\right] .\right.
\end{gathered}
$$

For the skew-product system (1.7), by using Lemmas 1.1 and 1.2 in [12], we set for $\forall\langle k, \omega\rangle \in \mathbb{R}$

$$
g_{i j}(k, \lambda)= \begin{cases}\prod_{\alpha_{u} \in \sigma\left(A_{i}\right), \beta_{v} \in \sigma\left(A_{j}\right)}\left(i\langle k, \omega\rangle-\left(\alpha_{u}(\lambda)-\beta_{v}(\lambda)\right),\right. & i \neq j ; \\ \prod_{\alpha_{u}, \alpha_{v} v \sigma\left(A_{i}\right), u \neq v} i\langle k, \omega\rangle-\left(\alpha_{u}(\lambda)-\alpha_{v}(\lambda)\right), & \mathrm{i}=\mathrm{j} .\end{cases}
$$

Remark: It is easily seen that if $A \in C^{\omega}(\Lambda, g)$ and the division of $\sigma(A)$ is sufficiently separated, then all $g_{i j}$ are analytic functions of $\lambda, \forall 1 \leq i, j \leq s$.

For the proof of this remark (see in [17]).
Thus, we assume the following:
Non-degeneracy Conditions: There exist an integer $d \geq 0$ and $\varsigma \geq 0$ such that

$$
\begin{equation*}
\max _{0 \leq l \leq d}\left|\frac{\partial^{l}}{\partial \lambda^{l}} g_{i j}(k, \lambda)\right|>\varsigma, \text { for all } 1 \leq i, j \leq s \tag{1.11}
\end{equation*}
$$

uniformly hold $\forall \lambda \in \Lambda$ and $\langle k, \omega\rangle \in \mathbb{R}$.
Remark: The condition (1.11) will assure that the small denominator condition always holds for the "most" parameter $\lambda$. Here, we take only those $k$ in which $|\langle k, \omega\rangle| \leq 2 \delta_{0}$, because for the large enough $|\langle k, \omega\rangle|$, we always see that the matrix $i\langle k, \omega\rangle I_{l_{i} l_{j}}-\left(I_{l_{i}} \otimes A_{j}(\lambda)-A_{i}^{T}(\lambda) \otimes I_{l_{j}}\right)$ is automatically nonsingular and the small denominator condition is satisfied. It can easily be seen that the condition (1.11) is weaker than the non-degeneracy condition (1.3) used by Jorba and Simó.

Moreover, the property that $g_{i j}(k, \lambda)$ depends analytically on $\lambda$ can be preserved under small perturbations, and at each iterative step, we will preserve the non-degeneracy conditions.

### 1.1. Statement of the main result

To state the main result, consider $Q$ as an analytic $g$-valued function that can be defined on a complex neighbourhood of $\mathbb{T}^{r} \times \Lambda$ :

$$
W_{h}\left(\mathbb{T}^{r} \times \Lambda\right)=\left\{(\vartheta, \lambda) \in \mathbb{C}^{r} \times \Lambda \mid \operatorname{dist}\left(\vartheta, \mathbb{T}^{r}\right)<h\right\},
$$

where $\lambda \in \Lambda=(a, b)$. Defined the norm of $Q$ as:

$$
\|Q\|_{h}=\max _{0 \leq I \leq d} \sup _{\left.(\vartheta, \lambda) \in W_{h} \mathbb{T}^{r} \times \Lambda\right)}\left|\frac{\partial^{l} Q}{\partial \lambda^{l}}\right|
$$

similarly

$$
\|A\|=\max _{0 \leq l \leq d} \sup _{\lambda \in \Lambda}\left|\frac{\partial^{l} A(\lambda)}{\partial \lambda^{l}}\right|
$$

where $\|\cdot\|$ denotes the matrix norm.
Theorem 1.1. Consider the skew-product system (1.7) in which $\omega$ is a fixed Brjuno vector and it satisfies the Brjuno-Rüssmann condition (1.6) and $A(\lambda)$ satisfies the non-degeneracy condition (1.11), and there exists $K>0$ such that $\|A\| \leq K$. Then there exist $\varepsilon>0, h>0$, such that if $\|Q(\cdot, \cdot)\|_{h}=\varepsilon_{1}<\varepsilon$, the measure of the set of parameter $\lambda^{\prime}$ s for which the system (1.7) is non-reducible is no larger than $C L\left(10 \varepsilon_{1}\right)^{c}$, with some positive constants $C, c$, and $L$ denotes the length of the parameter interval $\Lambda$.

## 2. Proof of the Theorem 1.1

Theorem 1.1 will be proven by KAM iteration. At each iterative step, we have a L-P transformation close to identity as

$$
\begin{equation*}
P(\varphi)=I+Z(\varphi) \tag{2.1}
\end{equation*}
$$

where $Z(\varphi) \in C_{h}^{\omega}\left(\mathbb{T}^{r}, g\right), P(\varphi) \in C_{h}^{\omega}\left(\mathbb{T}^{r}, G\right)$ and by using the L-P transformation (2.1), the quasi-periodic system $\frac{d x}{d t}=(A+Q) x$ is changed into

$$
\frac{d x}{d t}=\left(D_{\omega} P \cdot P^{-1}+P(A+Q) P^{-1}\right) x
$$

Since $Z$ is very small and in the expansion form $P^{-1}$ can be written as:

$$
P^{-1}=I-Z+Z^{2}+O\left(\|Z\|^{3}\right) .
$$

So, we have

$$
\begin{align*}
& D_{\omega} P \cdot P^{-1}+P(A+Q) P^{-1} \\
& =D_{\omega} Z\left(I-Z+Z^{2}+O\left(\|Z\|^{3}\right)\right)+(I+Z)(A+Q)\left(I-Z+Z^{2}+O\left(\|Z\|^{3}\right)\right) \\
& =A+D_{\omega} Z+[Z, A]+Q-D_{\omega} Z \cdot Z+[Z, Q]+A Z^{2}-Z A Z+O\left(\|Z\|^{3}\right) \tag{2.2}
\end{align*}
$$

In general, we have to find a small $Z$ in which the transformed system is still of the form $\frac{d x}{d t}=$ $\left(A^{+}+Q^{+}\right) x$, where $A^{+}$is block-diagonal as $A$ and $Q^{+}$is much smaller than $Q$.
To do this, we have to calculate $Z$ solving the following linearized equation

$$
\begin{equation*}
D_{\omega} Z-[A, Z]=-Q \tag{2.3}
\end{equation*}
$$

where $[A, Z]=A Z-Z A$ and to prove

$$
Q^{+}=-D_{\omega} Z \cdot Z+[Z, Q]+A Z^{2}-Z A Z+O\left(\|Z\|^{3}\right)
$$

is more smaller.

### 2.1. Solution of the linearized equation

In this subsection, we will solve the linearized equation, for this we need the following:
Definition: Let $u=\left(u_{1}, \cdots, u_{m}\right) \in \mathbb{T}^{m}$. Its norm is denoted by $\|u\|$ and is defined as:

$$
\|u\|=\max _{1 \leq i \leq m}\left|u_{i}\right|
$$

Definition: For a $m \times m$ matrix $S=\left(s_{i j}\right)$, its operator norm is denoted by $\|S\|$ and is equivalent to $m \times \max \left|s_{i j}\right|$.
Notation: Let $F \in C_{h}^{\omega}\left(\mathbb{T}^{r} \times \Lambda, g\right)$ and its Fourier series is $F=\sum_{k \in \mathbb{Z}^{r}} F_{k} e^{i\langle k, \varphi\rangle}$, then the $k^{\text {th }}$ Fourier coefficients of $F$ denoted by $F_{k}$, given by $F_{k}=\int_{\mathbb{T}^{r}} e^{-i\langle k, \varphi\rangle} F(\varphi) d \varphi$.
Remark 2.1. For $F \in C_{h}^{\omega}\left(\mathbb{T}^{r} \times \Lambda, g\right)$, we have

$$
\left|F_{k}\right| \leq|F|_{h} e^{-|k| h}
$$

Note. For $k \in \mathbb{Z}^{d}$, we denote $|k|=\sum_{n=1}^{d}\left|k_{n}\right|$. Similarly, for a function $f$, its modulus is denoted by $|f|$.
Throughout the discussion, to simplify notations, the letters $c, C$ denote different positive constants.
By substituting the Fourier series expansions of $Z, Q$ into the Eq (2.3), and then by equating the corresponding Fourier coefficients on both sides, we obtain

$$
\begin{equation*}
i\langle k, \omega\rangle Z_{k}-\left(A Z_{k}-Z_{k} A\right)=-Q_{k} \tag{2.4}
\end{equation*}
$$

suppose that the eigenvalues of the linear operator $i\langle k, \omega\rangle I_{d}+[A, \cdot]$ in the left part are

$$
i\langle k, \omega\rangle-\left(\alpha_{i}-\alpha_{j}\right), \quad 1 \leq i, j \leq n, \quad \alpha_{i}, \alpha_{j} \in \sigma(A)
$$

The eigenvalues will be $\alpha_{i}-\alpha_{j}$ for $k=0$. As the considered matrix $A=\operatorname{diag}\left(A_{1}, \cdots, A_{s}\right)$ is a block-diagonal with different blocks $A_{i}, A_{j}$ and each block have different eigenvalues, i.e. $\alpha_{u} \neq \beta_{v}$ if $\alpha_{u} \in A_{i}, \beta_{v} \in A_{j}$ for $i \neq j$, from conclusions as seen from other researchers [12,17-20], we see that the matrix $I_{l_{i}} \otimes A_{j}-A_{i}^{T} \otimes I_{l_{j}}$ is non-singular if $i \neq j$.

In block-diagonal form, let $Q_{k}$ can be written as $\left(Q_{k i j}\right)$, where $Q_{k i j}$ is a matrix of order $l_{i} \times l_{j}$ $, 1 \leq i, j \leq s$ and $l_{i}, l_{j}$ are the orders of matrices $A_{i}, A_{j}$ respectively.

Now, for $k=0$, we solve the equation (2.4). Suppose

$$
Q_{0}^{d}=\left(Q_{011}, \cdots, Q_{0 s s}\right)
$$

and

$$
Q_{0}^{*}=Q_{0}-Q_{0}^{d} .
$$

For $k=0$, the equation (2.4) can be written as

$$
\begin{equation*}
A Z_{0}-Z_{0} A=Q_{0} \tag{2.5}
\end{equation*}
$$

Equation (2.5) can not be solved completely because the eigenvalues involved the multiplicity. However, the following equation

$$
A Z_{0}-Z_{0} A=Q_{0}^{*}
$$

has a solution $Z_{0}=\left(Z_{0 i j}\right)$ with $Z_{0 i i}=0$ and

$$
A_{i} Z_{0 i j}-Z_{0 i j} A_{j}=Q_{0 i j}, \text { for } i \neq j
$$

has the unique solution $Z_{0 i j}$.
Moreover, we have the estimate [12]

$$
\begin{align*}
\left\|J_{i j}^{-1}(0, \lambda)\right\| & \leq \max _{i \neq j}\left\|\left[I_{l_{j}} \otimes A_{i}(\lambda)-A_{j}^{T}(\lambda) \otimes I_{l_{i}}\right]^{-1}\right\| \\
& \leq c \frac{n K^{l l_{j}}}{\varrho^{l_{i} l_{j}}} \leq C(\varrho, n) K^{l_{i} l_{j}}, \tag{2.6}
\end{align*}
$$

and

$$
\max _{0 \leq \leq \leq r}\left\|\frac{\partial^{l}}{\partial \lambda^{l}} J_{i j}^{-1}(0, \lambda)\right\|=\max _{1 \leq \leq \leq r}\left\|\frac{\partial^{l}}{\partial \lambda^{l}}\left(\frac{a d J_{i j}}{d e t J_{i j}}\right)\right\|
$$

$$
\leq C(\varrho, n, r) K^{\left(l_{i j}\right)^{2}}
$$

as $\operatorname{dist}\left(\sigma\left(A_{i}(\lambda)\right), \sigma\left(A_{j}(\lambda)\right)\right)>\varrho>0$, for $i \neq j$. Moreover, we get

$$
\begin{align*}
\max _{0 \leq l \leq r}\left\|\frac{\partial^{l}}{\partial \lambda^{l}} Z_{0}(\lambda)\right\| & \leq C \max _{0 \leq l \leq r} \| \frac{\partial^{l}}{\partial \lambda^{l}}\left(J_{i j}^{-1}(0, \lambda)\|\cdot\| \frac{\partial^{l}}{\partial \lambda^{l}} Q_{0}(\lambda) \|\right. \\
& \leq C(\varrho, n, r) K^{n^{4}} \max _{0 \leq \leq r}\left\|\frac{\partial^{l}}{\partial \lambda^{l}} Q_{0}(\lambda)\right\| . \tag{2.7}
\end{align*}
$$

Now, we solve the Eq (2.4) for $k \neq 0$. From Lemma 3.2 as seen in [12], the solution of (2.4) is equivalent to the solution of the following vector equation

$$
\begin{equation*}
J(k, \lambda) Z_{k}^{\prime}(\lambda)=-Q_{k}^{\prime}(\lambda) \tag{2.8}
\end{equation*}
$$

By using corollaries [12], Eq (2.8) is solvable $\Longleftrightarrow$ the matrix $J(k, \lambda)$ is invertible. Suppose $P=I+\sum Z_{k}$ is a L-P transformation. Then by using the L-P transformation, the new system becomes

$$
\frac{d x}{d t}=\left(A^{+}+Q^{+}\right) x
$$

where

$$
\begin{align*}
& A^{+}=A+Q_{0}^{d} \\
& Q^{+}=-D_{\omega} Z \cdot Z^{-1}+[Z, Q]+A Z^{2}-Z A Z+O\left(\|Z\|^{3}\right) \tag{2.9}
\end{align*}
$$

Since $A$ and $Q_{0}^{d}$ are block-diagonal matrices, therefore $A^{+}$is also a block-diagonal. Next, we will show that in a smaller domain $Q^{+}$is much smaller and the non-degeneracy condition is satisfied by $A^{+}$. Estimation of $Q^{+}$.

First of all, we estimate $Z_{k}$. Actually, to control the solution of $Z_{k}$, we need the following small denominator condition, i.e. if there exist $N>0$ such that $\forall i, j$

$$
\begin{equation*}
\left|g_{i j}(k, \lambda)\right| \geq \frac{N^{-1}}{\Delta(|k|)}, \quad 1 \leq i, j \leq s . \tag{2.10}
\end{equation*}
$$

where $\Delta$ is an approximation function as defined above.
In order to estimate $Z_{k}$, we need to estimate the operator $J_{i j}^{-1}(k, \lambda)$ for $k \neq 0$.
Lemma 2.1. For $k \neq 0$ and the small denominator conditions (2.10) are satisfied by all parameters $\lambda$, then we have

$$
\begin{gather*}
\left\|J_{i j}^{-1}(k, \lambda)\right\| \leq c K^{l^{l} l_{j}} N(\Delta(|k|))^{l^{l} l_{j}}, \quad i \neq j,  \tag{2.11}\\
\left\|J^{-1}(k, \lambda)\right\| \leq c K^{n^{2}} \alpha^{n} N^{n^{2}}(\Delta(|k|))^{n^{2}},  \tag{2.12}\\
\max _{0 \leq l \leq r}\left\|\frac{\partial^{l}}{\partial \lambda^{l}} J^{-1}(k, \lambda)\right\| \leq c K^{n^{4}} \alpha^{2^{r} n} N^{2^{r} n^{2}}(\Delta(|k|))^{2^{r} n^{2}} . \tag{2.13}
\end{gather*}
$$

where c denotes constant.

Proof. Since $J_{i j}$ is a non-singular matrix, so its inverse is defined as $J_{i j}^{-1}=a d J_{i j} / \operatorname{det} J_{i j}$. By the small denominator conditions (2.10), we have

$$
|J(k, \lambda)|=\left|\left[i\langle k, \omega\rangle I_{n^{2}}+\left(I_{n} \otimes A(\lambda)-A^{T}(\lambda) \otimes I_{n}\right)\right]\right| \geq\left(N^{-1}\right)^{n^{2}}\left(\frac{\alpha^{-1}}{\Delta(|k|)}\right)^{n}
$$

and

$$
\left|J_{i j}(k, \lambda)\right|=\left|\left[i\langle k, \omega\rangle I_{l_{i} l_{j}}+\left(I_{l_{i}} \otimes A_{j}(\lambda)-A_{i}^{T}(\lambda) \otimes I_{l_{j}}\right)\right]\right| \geq\left(N^{-1}\right)^{l_{i l j}}\left(\frac{\alpha^{-1}}{\Delta(|k|)}\right)^{l_{i}}
$$

using the definition of the norm $\left\|J_{i j}\right\|$ and the small denominator condition (2.10), the estimate (2.11)can be found easily. Also as $\operatorname{det} J=\prod_{1 \leq i, j \leq s} \operatorname{det} J_{i j}$, similarly we can calculate the estimations (2.12) and (2.13).

For $k \neq 0$, from Eq (2.8), we have

$$
\begin{equation*}
Z_{k}^{\prime}(\lambda)=-J^{-1}(k, \lambda) Q_{k}^{\prime}(\lambda) \tag{2.14}
\end{equation*}
$$

as $Z_{k}^{\prime}, Q_{k}^{\prime}$ are the transpose of $Z_{k}$ and $Q_{k}$ respectively, therefore it is easy to prove $\left\|Z_{k}\right\|=\left\|Z_{k}^{\prime}\right\|,\left\|Q_{k}\right\|=$ $\left\|Q_{k}^{\prime}\right\|$ (see in [12] for the proof).
In our article, we represent $F(\lambda)$ a $\lambda$-dependent matrix as:

$$
|F(\lambda)|=\max _{0 \leq l \leq r}\left\|\frac{\partial^{l} F(\lambda)}{\partial \lambda^{l}}\right\| .
$$

Since $Q \in C_{h}^{\omega}\left(\mathbb{T}^{r} \times \Lambda, g\right)$, then by the Remark 2.1, we have

$$
\left|Q_{k}\right| \leq|Q|_{h} e^{-|k| h}
$$

As a result, for $k \neq 0$ and for any $0<\bar{h}<h$, we have

$$
\begin{aligned}
\left|Z_{k}(\lambda)\right| & \leq\left|J^{-1}(k, \lambda) \| Q_{k}(\lambda)\right| \\
& \leq C K^{n^{4}} \alpha^{2^{r} n} N^{2^{r^{2}}}(\Delta(|k|))^{r^{r} n^{2}}|Q|_{h} e^{-|k| h}
\end{aligned}
$$

or

$$
\begin{equation*}
\left|Z_{k}(\lambda)\right| \leq C K^{n^{4}} \alpha^{2^{r} n} N^{2^{r} n^{2}}(\Delta(|k|))^{2^{r} n^{2}}|Q|_{h} e^{-|k|(h-\bar{h})} e^{-|k| \bar{h}} \tag{2.15}
\end{equation*}
$$

In particular, take an approximation function $\Delta(t)=e^{t^{\delta}}, \delta<1$, which satisfy the Brjuno-Rüssmann condition (1.6), since the function $e^{t^{\delta} 2^{r} n^{2}} \cdot e^{-t(h-\bar{h})}$ has the maximal value at $t=\left(\frac{2^{r} r^{2} \delta}{h-\bar{h}}\right)^{\frac{-1}{\delta-1}}$, one has

$$
\begin{align*}
\left|Z_{k}(\lambda)\right| & \leq C K^{n^{4}} \alpha^{2^{r} n} N^{2^{r} n^{2}}|Q|_{h} e^{\left.\left[2^{r} n^{2}\left(\frac{2^{r} n^{2} \delta}{h-h}\right) \frac{-\delta}{\delta-1}-\left(\frac{2^{r} h^{2} \delta}{h-h}\right)\right)^{\frac{-1}{\delta-1}(h-\bar{h})}\right]} e^{-|k| \bar{h}} \\
& \leq C(n, r, \delta, \alpha) K^{n^{4}} N^{2^{r} n^{2}}\left[\frac{|Q|_{h}}{(h-\bar{h})^{\frac{\delta^{2}-\delta-1}{\delta-1}}}-\frac{|Q|_{h}}{(h-\bar{h})^{\frac{\delta}{\delta-1}}}\right] e^{-|k| \bar{h}} . \tag{2.16}
\end{align*}
$$

Consider

$$
Z(t, \lambda)=\sum_{k \in \mathbb{Z}^{r}} Z_{k}(\lambda) e^{i(k, t\rangle}
$$

choose $h^{\prime}: 0<h^{\prime}<\bar{h}$ s.t. if $\bar{h}-h^{\prime}=h-h^{\prime}<1$. So, using the Lemma 4 in [7], we obtain

$$
\begin{align*}
|Z|_{h^{\prime}} & \leq \sum_{k \in \mathbb{Z}^{r}}\left|Z_{k}\right| e^{|k| h^{\prime}} \\
& \leq C K^{n^{4}}\left|Q_{0}\right|+C K^{n^{4}} N^{2^{r} n^{2}}\left[\frac{|Q|_{h}}{(h-\bar{h})^{\frac{\delta^{2}-\delta-1}{\delta-1}}}-\frac{|Q|_{h}}{(h-\bar{h})^{\frac{\delta}{\delta-1}}}\right] \sum_{\left.k \in \mathbb{Z}^{r} \backslash \backslash 0\right\}} e^{-\left(\bar{h}-h^{\prime}\right)|k|} \\
& \leq C K^{n^{4}} N^{2^{2} n^{2}}\left[\frac{|Q|_{h}}{(h-\bar{h})^{\frac{\delta^{2}-\delta-1}{\delta-1}}}-\frac{|Q|_{h}}{(h-\bar{h})^{\frac{\delta}{\delta-1}}}\right]\left(\frac{2}{\bar{h}-h^{\prime}}\right)^{m} e^{\frac{\left(\bar{h}-h^{\prime}\right) m}{2}} \\
& \leq C(n, r, \delta, \alpha, m) K^{n^{4} N^{2^{r} n^{2}}}\left[\frac{1}{\left(h-h^{\prime}\right)^{\frac{\delta^{2}-\delta-1}{\delta-1}+m}}-\frac{1}{\left(h-h^{\prime}\right)^{\frac{\delta}{\delta-1}+m}}\right]|Q|_{h} . \tag{2.17}
\end{align*}
$$

Let $s=\frac{\delta^{2}-\delta-1}{\delta-1}+m$, and $s^{\prime}=\frac{\delta}{\delta-1}+m$, we get

$$
\begin{equation*}
|Z|_{h^{\prime}} \leq C K^{n^{4}} N^{2^{r} n^{2}}\left[\frac{1}{\left(h-h^{\prime}\right)^{s}}-\frac{1}{\left(h-h^{\prime}\right)^{s^{\prime}}}\right]|Q|_{h} . \tag{2.18}
\end{equation*}
$$

similarly, we can find

$$
\begin{gathered}
\left|D_{\omega} Z\right|_{h^{\prime}} \leq C K^{n^{4}} N^{2^{r} n^{2}}\left[\frac{1}{\left(h-h^{\prime}\right)^{s+1}}-\frac{1}{\left(h-h^{\prime}\right)^{s^{\prime}+1}}\right]|Q|_{h} \\
\left|D_{\omega} Z \cdot Z\right|_{h^{\prime}} \leq C K^{n^{4}} N^{2^{r^{2}}}\left[\frac{1}{\left(h-h^{\prime}\right)^{2 s+1}}-\frac{1}{\left(h-h^{\prime}\right)^{2 s^{\prime}+1}}\right]|Q|_{h}^{2} \\
\left|A Z^{2}\right|_{h^{\prime}}=|Z A Z|_{h^{\prime}} \leq C K^{n^{4}} N^{2^{\prime} n^{2}}\left[\frac{1}{\left(h-h^{\prime}\right)^{2 s}}-\frac{1}{\left(h-h^{\prime}\right)^{2 s^{\prime}}}\right]|Q|_{h}^{2} \\
|[Z, Q]|_{h^{\prime}} \leq 2|Z|_{h^{\prime}} \cdot|Q|_{h} \leq C K^{n^{4}} N^{2^{r} n^{2}}\left[\frac{1}{\left(h-h^{\prime}\right)^{s}}-\frac{1}{\left(h-h^{\prime}\right)^{s^{s}}}\right]|Q|_{h}^{2}
\end{gathered}
$$

Hence, from Eq (2.9), we get

$$
\begin{equation*}
\left|Q^{+}\right|_{h^{\prime}} \leq C K^{2 n^{4}+1} N^{2^{r+1} n^{2}}\left[\frac{1}{\left(h-h^{\prime}\right)^{2 s+1}}-\frac{1}{\left(h-h^{\prime}\right)^{2 s^{\prime}+1}}\right]|Q|_{h}^{2} \tag{2.19}
\end{equation*}
$$

## Verification of the non-degeneracy conditions for $A^{+}$.

Since

$$
A^{+}=A+Q_{0}^{d}=\operatorname{diag}\left(A_{1}+Q_{011}, \cdots, A_{s}+Q_{0 s s}\right)
$$

Let

$$
D_{i j}^{+}(k, \lambda)=\operatorname{det}\left[i\langle k, \omega\rangle I_{l_{i l} l_{j}}+\left(I_{l_{i}} \otimes\left(A_{j}(\lambda)+Q_{0 j j}(\lambda)\right)-\left(A_{i}^{T}(\lambda)+Q_{0 i i}^{T}(\lambda)\right) \otimes I_{j}\right)\right]
$$

The new determinant $D_{i j}^{+}$is analytic with respect to $\lambda$ as well.

The above determinant can be rewritten as

$$
D_{i j}^{+}(k, \lambda)=D_{i j}(k, \lambda)+Y_{i j}(k, \lambda) .
$$

where $\left.D_{i j}(k, \lambda)=\operatorname{det}\left[i\langle k, \omega\rangle I_{l_{i} l_{j}}+\left(I_{l_{i}} \otimes A_{j}(\lambda)-A_{i}^{T}(\lambda)\right) \otimes I_{j}\right)\right]$ and $Y_{i j}(k, \lambda)$ is a summary of $2^{l_{i} l_{j}}-1$ determinants denoted by $y_{t}(k, \lambda)\left(1 \leq t \leq 2^{l_{i} l_{j}}-1\right)$. Furthermore, there exist at least one column in each determinant $y_{t}$ such that the entries in this column are either 0 or of the form $c-d$, where $c$ and $d$ are entries of $Q_{0 j j}$ and $Q_{0 i i}$ respectively.

As $\left|Q_{0}^{d}\right|_{h} \leq|Q|_{h}<\varepsilon$, we get

$$
\left|\frac{\partial^{l}}{\partial \lambda^{l}} D_{i j}^{+}(k, \lambda)\right| \leq C|A| \varepsilon, \text { for } 1 \leq l \leq r .
$$

similarly,

$$
\begin{equation*}
\left|\frac{\partial^{l}}{\partial \lambda^{l}}\left(g_{i j}^{+}(k, \lambda)-g_{i j}(k, \lambda)\right)\right| \leq C|A| \varepsilon, \text { for } 1 \leq l \leq r . \tag{2.20}
\end{equation*}
$$

So, we have

$$
\begin{equation*}
\left|\frac{\partial^{l}}{\partial \lambda^{l}} g_{i j}^{+}(k, \lambda)\right| \geq \varsigma-C|A| \varepsilon \geq \varsigma-C K \varepsilon=\varsigma^{\prime}, \text { for } 1 \leq l \leq r . \tag{2.21}
\end{equation*}
$$

The proof is obvious. Note that, here we only need to choose such $k^{\prime} s$ so that $|(k, \lambda)|$ is not large enough, i.e., $|(k, \lambda)| \leq C K$, where $|A| \leq K$, because for large enough $|(k, \lambda)|$, the matrix $J(k, \lambda)$ becomes automatically non-singular. So, when $|(k, \lambda)|$ has large values, then $J^{+}(k, \lambda)$ becomes naturally nonsingular and no need to preserve non-degenerate property.

Alternatively, we know from the perturbation theory of matrices that the continuous change of eigenvalues depends on the entries, and by Ostrowski theorem (see [21]), the distance between eigenvalues of any two blocks can be estimated as

$$
\min _{i \neq j} \operatorname{dist}\left(\sigma\left(A_{i}^{+}\right), \sigma\left(A_{j}^{+}\right)\right)=\varrho^{+}>\varrho-c \varepsilon^{\frac{1}{n}} .
$$

Now, we summarize the above discussions in the following conclusion.

## Conclusion 1.

Consider $\Lambda$ subset of (a,b) be some parameter segment, a one parameter family of constant elements $A \in C^{\omega}(\Lambda, g)$, and $Q \in C_{h}^{\omega}\left(\mathbb{T}^{r} \times \Lambda, g\right)$ be the perturbation. Suppose that there exist $K, \varepsilon, N>0$ s.t.

- $|A| \leq K, \quad|Q|_{h}<\varepsilon$,
- for all $\lambda \in \Lambda$, the non-degeneracy conditions (1.11) and the small denominator conditions (2.10) hold.
Then, $\exists h^{\prime}>0$ and a map $Z \in C_{h^{\prime}}^{\omega}\left(\mathbb{T}^{r} \times \Lambda, g\right)$, and

$$
\begin{gathered}
A^{+} \in C^{\omega}(\Lambda, g) \\
Q^{+} \in C_{h^{\prime}}^{\omega}\left(\mathbb{T}^{r} \times \Lambda, g\right),
\end{gathered}
$$

such that

1) $A^{+}=A+Q_{0}^{d}, A^{+}+Q^{+} \equiv A+Q$
2) We have the estimation (2.19), i.e. $\left|Q^{+}\right|_{h^{\prime}} \leq C K^{2 n^{4}+1} N^{2^{r+1} n^{2}}\left[\frac{1}{\left(h-h^{\prime}\right)^{2 s+1}}-\frac{1}{\left(h-h^{\prime}\right)^{s^{\prime}+1}}\right]|Q|_{h^{2}}^{2}$.
3) We have preserved the non-degeneracy conditions .i.e., $\max _{0 \leq \leq \leq r}\left|\frac{\partial^{l}}{\partial \lambda^{\prime}} g_{i j}^{+}(k, \lambda)\right| \geq \varsigma^{\prime}$.
4) $\varrho^{+}>\varrho-c \varepsilon^{\frac{1}{n}}, K^{+}<K+\varepsilon$.

### 2.2. Iteration

In this subsection, we will prove that the perturbation $Q$ goes to zero very quickly provided that the small divisor conditions hold.

First of all, consider the following two iterative sequences:

$$
\begin{gather*}
h_{m}=\left(\frac{1}{2}+\frac{1}{2^{m}}\right) h_{1},  \tag{2.22}\\
N_{m}=\left(\frac{\left(\frac{6}{5}\right)^{m}+\frac{1}{\eta}}{h_{m-1}-h_{m}}\right)^{\gamma}=\left(h_{1}\right)^{-\gamma} 2^{m \gamma}\left(\left(\frac{6}{5}\right)^{m}+\frac{1}{\eta}\right)^{\gamma} \tag{2.23}
\end{gather*}
$$

where $\gamma \geq r$ is a constant, and $\eta$ will be considered as in the following lemma
Lemma 2.2. There exist positive constants $\eta<1$, , s. s.t., if $\varepsilon_{1}$ is sufficiently small, then $\forall m \geq 1$

$$
\begin{aligned}
& \varepsilon_{m} \leq \eta^{b} e^{-\left(\frac{6}{5}\right)^{m}} \\
& K_{m} \leq 2^{m-1} K_{1} .
\end{aligned}
$$

Proof. Suppose that if we do this up to $m^{\text {th }}$ step, we have

$$
\left|Q_{m}\right|_{h_{m}} \leq \varepsilon_{m} \leq \eta^{b} e^{-\left(\frac{6}{5}\right)^{m}}
$$

and

$$
K_{m} \leq K_{m-1}+\varepsilon_{m-1} \leq 2^{m-1} K_{1}
$$

By induction, we need to prove that

$$
\begin{equation*}
\left|Q_{m+1}\right|_{h_{m+1}} \leq \eta^{b} e^{-\left(\frac{6}{5}\right)^{m+1}} \tag{2.24}
\end{equation*}
$$

and

$$
\begin{equation*}
K_{m+1} \leq 2^{m} K_{1} . \tag{2.25}
\end{equation*}
$$

Indeed Eq (2.25) is satisfied as

$$
K_{m+1} \leq K_{m}+\varepsilon_{m} \leq K_{m}+\eta^{b} e^{-\left(\frac{6}{5}\right)^{m}} \leq K_{m}+1 \leq 2 K_{m} \leq 2 \cdot 2^{m-1} K_{1}=2^{m} K_{1} .
$$

And from Eq (2.19), we have

$$
\varepsilon_{m+1} \leq C K_{m}^{2 n^{4}+1} N_{m}^{2^{r+1} n^{2}}\left[\frac{1}{\left(h_{m}-h_{m+1}\right)^{2 s+1}}-\frac{1}{\left(h_{m}-h_{m+1}\right)^{2 s^{\prime}+1}}\right] \varepsilon_{m}^{2}
$$

To prove Eq (2.24), we need

$$
C K_{m}^{2 n^{4}+1} N_{m}^{2^{r+1} n^{2}}\left[\frac{1}{\left(h_{m}-h_{m+1}\right)^{2 s+1}}-\frac{1}{\left(h_{m}-h_{m+1}\right)^{2 s^{\prime}+1}}\right] \eta^{2 b} e^{-\left(\frac{6}{5}\right)^{2 m}} \leq \eta^{b} e^{-\left(\frac{6}{5}\right)^{m+1}} .
$$

Then by using Eqs (2.22) and (2.25), we have

$$
\begin{equation*}
C K_{1}^{2 n^{4}+1} h_{1}^{-(2 s+1)} 2^{m\left(2 n^{4}+1\right)+(m+1)(2 s+1)} N_{m}^{2^{r+1} n^{2}} \eta^{2 b} e^{-(4 / 5)\left(\frac{6}{5}\right)^{m}} \leq 1 . \tag{2.26}
\end{equation*}
$$

Let $R_{m}(\eta)=N_{m}^{2^{r+1} n^{2}} \eta^{b-1}$, if we choose

$$
\begin{equation*}
b>2^{r+1} n^{2} \gamma+1, \tag{2.27}
\end{equation*}
$$

then by Eq (2.23) we see that for smaller value of $\eta$, the value of $R_{m}$ also goes smaller. Now, firstly we set $\eta=\eta_{0}<1$. As the sequence

$$
2^{m\left(2 n^{4}+1\right)+(m+1)(2 s+1)+m r} R_{m}\left(\eta_{0}\right) e^{-(4 / 5)\left(\frac{6}{5}\right)^{m}},
$$

is bounded from above,let's denote its maximum by $\bar{\beta}$. In order to satisfy Eq (2.26), it is enough to choose $\eta$ s.t.

$$
C K_{1}^{2 n^{4}+1} h_{1}^{-(2 s+1)} \bar{\beta} \eta \leq 1 .
$$

Thus, define

$$
\eta \leq \min \left\{C K_{1}^{-\left(2 n^{4}+1\right)} h_{1}^{2 s+1} \bar{\beta}^{-1}, \eta_{0}\right\},
$$

and so we obtained the $\mathrm{Eq}(2.26)$. If we choose $\eta=\left(10 \varepsilon_{1}\right)^{1 / b}$, then it is enough to take

$$
\begin{equation*}
\varepsilon_{1} \leq \min \left\{\frac{C K_{1}^{-b\left(2 n^{4}+1\right)} h_{1}^{b(2 s+1)}}{10 \beta^{b}}, \eta^{b} e^{-\frac{6}{5}}\right\} . \tag{2.28}
\end{equation*}
$$

Hence, the proof of lemma is finished.
From Eq (2.18), it can be seen that the sequence $\left|Z_{m}\right|_{h_{m}}$ converges to 0 with super-exponential velocity, then by the transformation $P_{m}=I+Z_{m}$, we have $P_{m} \rightarrow I$, and so the composition of transformations $P_{m} \circ P_{m-1} \circ \cdots \circ P_{1}$ will also be convergent. On the other hand, from conclusion 1, we have

$$
\varsigma_{m} \geq \varsigma_{m-1}-C K_{m} \varepsilon_{m},
$$

so

$$
\begin{equation*}
\varsigma_{m} \geq \varsigma-C \sum_{1 \leq i \leq m-1} K_{i} \varepsilon_{i} \geq \frac{\varsigma}{2}, \tag{2.29}
\end{equation*}
$$

for small enough $\varepsilon_{1}$. Thus, the preservation of the non-degeneracy conditions is proved. By the way, for small enough $\varepsilon_{1}$, we also have the estimate

$$
\begin{equation*}
\varrho_{m} \geq \varrho-C \sum_{1 \leq i \leq m-1} \varepsilon_{i}^{\frac{1}{n}} \geq \frac{\varrho}{2} . \tag{2.30}
\end{equation*}
$$

### 2.3. Measure of the removed set

In this subsection, we will show that the set of parameters satisfying the small denominator conditions is of the large Lebesgue measure. In the end, we estimate the measure of the removed parameter set. At the $m^{\text {th }}$ step, for $\forall i, j, 1 \leq i, j \leq s$, we denote the removed set as:

$$
R_{k i j}^{m}=\left\{\lambda:\left|g_{i j}^{m}(k, \lambda)\right| \leq \frac{N_{m}^{-1}}{\Delta(|k|)}\right\}
$$

and consider

$$
\begin{aligned}
& R_{k}^{m}=\bigcup_{1 \leq i, j \leq s} R_{k i j}^{m}, \\
& R^{m}=\bigcup_{0 \neq k \in \mathbb{Z}^{r}} R_{k}^{m} .
\end{aligned}
$$

To calculate the estimate for the measure of $R_{k i j}^{m}$, the following lemma is needed:
Lemma 2.3. Consider $g(x)$ is a $C^{M}$ function on the closure $\bar{I}$, where $I \in R^{1}$ is an interval of length $L$. Let $I_{h}=\{x:|g(x)| \leq h, h>0\}$. If for some constant $r>0,\left|g^{(M)}(x)\right| \geq r$ for $\forall x \in I$, then $\left|I_{h}\right| \leq c L h^{1 / M}$, where $\left|I_{h}\right|$ denotes the Lebesgue measure of $I_{h}$ and constant $c=2\left(2+3+\cdots+M+r^{-1}\right)$.

For the proof, see [22].
Then, let $L$ denotes the length of the parameter interval $\Lambda$, and using above Lemma 2.3, we obtain

$$
\operatorname{mes}\left(R_{k i j}^{m}\right) \leq c L\left(\frac{N_{m}^{-1}}{\Delta(|k|)}\right)^{1 / r}
$$

where $c=2(2+3+\cdots+r+2 / \varsigma)$, as $g_{i j}^{m}(k, \lambda) \in C^{m}(\Lambda)$ and using the non-degeneracy conditions and Eq (2.30). Thus,

$$
m e s\left(R^{m}\right) \leq C n^{2} L N_{m}^{-\frac{1}{r}} \sum_{0 \neq k \in \mathbb{Z}^{r}}\left(\frac{1}{\Delta(|k|)}\right)^{1 / r} .
$$

For $\Delta(|k|)=e^{|k|^{\delta}}, \delta<1$, we have

$$
\begin{aligned}
m e s\left(R^{m}\right) & \leq C n^{2} L N_{m}^{-\frac{1}{r}} \sum_{0 \neq k \in \mathbb{Z}^{r}} e^{-|k|^{\delta} / r} \\
& \leq C(n, r, \delta, \varsigma) L N_{m}^{-\frac{1}{r}} .
\end{aligned}
$$

By Eq (2.23), $N_{m}>\frac{2^{m} \gamma}{\eta^{\gamma}}$, we have

$$
N_{m}^{-\frac{1}{r}} \leq \eta^{\frac{\gamma}{r}} \cdot \frac{1}{2^{\frac{m \gamma}{r}}} .
$$

Therefore, for $\eta=\left(10 \varepsilon_{1}\right)^{\frac{1}{b}}$ and $\gamma \geq r$, one has

$$
\begin{aligned}
\operatorname{mes}\left(\bigcup_{m=1}^{\infty} R^{m}\right) & \leq C L \eta^{\frac{\gamma}{r}} \sum_{m=1}^{\infty} 2^{\frac{-m \gamma}{r}} \leq C L \eta^{\frac{\gamma}{r}} \\
& \leq C(n, r, \delta, \varsigma, \gamma, \varrho) L\left(10 \varepsilon_{1}\right)^{c}, \text { where, } c=\frac{\gamma}{b r}
\end{aligned}
$$

Hence, the proof of the main result is completed.

## 3. Conclusions

In this article, we discussed the positive measure reducibility for quasi-periodic linear systems and proved that the system (1.7) is reduced to a constant coefficient system. The result was proved for a Brjuno vector $\omega$ and small parameter $\lambda$ by using the KAM method, Brjuno-Rüssmann condition and non-degeneracy condition.

## Acknowledgments

The authors extend their appreciation to the Yibin University, Yibin, China.

## Conflict of interest

The authors declare no conflicts of interest in this paper.

## References

1. R. Johnson, J. Moser, The rotation number for almost periodic potentials, Commun. Math. Phys., 84 (1982), 403-438. https://doi.org/10.1007/BF01208484
2. W. Coppel, Pseudo-autonomous linear systems, Bull. Aust. Math. Soc., 16 (1977), 61-65. https://doi.org/10.1017/S0004972700023005
3. R. A. Johnson, G. R. Sell, Smoothness of spectral subbundles and reducibility of quasi-periodic linear differential systems, J. Differ. Equ., 41 (1981), 262-288. https://doi.org/10.1016/0022-0396(81)90062-0
4. N. N. Bogoljubov, J. A. Mitropolski, A. M. Samoilenko, Methods of accelerated convergence in nonlinear mechanics, New York: Springer-Verlag, 1976.
5. E. I. Dinaburg, Y. G. Sinai, The one dimensional Schrödinger equation with a quasi-periodic potential, Funct. Anal. Appl., 9 (1975), 279-289. https://doi.org/10.1007/BF01075873
6. H. Rüssmann, On the one-dimensional Schrödinger equation with a quasi-periodic potential, Ann. NY. Acad. Sci., 357 (1980), 90-107. https://doi.org/10.1111/j.1749-6632.1980.tb29679.x
7. A. Jorba, C. Simó, On the reducibility of linear differential equations with quasiperiodic coefficients, J. Differ. Equ., 98 (1992), 111-124. https://doi.org/10.1016/0022-0396(92)90107-X
8. J. X. Xu, On the reducibility of linear differential equations with quasiperiodic coefficients, Mathematika, 46 (1999), 443-451. https://doi.org/10.1112/S0025579300007907
9. L. H. Eliasson, Floquet solutions for the 1-dimensional quasi-periodic Schrodinger equation, Commun. Math. Phys., 146 (1992), 447-482. https://doi.org/10.1007/BF02097013
10. R. Krikorian, Reductibility des systems produits-croiss a valeurs dans des groupes compacts, Astérisque, 1999.
11. L. H. Eliasson, Almost reducibility of linear quasi-periodic systems, Amer. Math. Soc., Providence, RI, 2001.
12. H. L. He, J. G. You, An improved result for positive measure reducibility of quasi-periodic linear systems, Acta. Math. Sinica., 22 (2006), 77-86. https://doi.org/10.1007/s10114-004-0473-5
13. D. F. Zhang, J. X. Xu, X. C. Wang, A new KAM iteration with nearly infinitely small steps in reversible systems of polynomial character, Qual. Theory Dyn. Syst., 17 (2018), 271-289. https://doi.org/10.1007/s 12346-017-0229-0
14. C. Chavaudret, S. Marmi, Reducibility of quasi-periodic cocycles under a Brjuno-Rüssmann arithmetical condition, JMD, 6 (2012), 59-78. https://doi.org/10.3934/jmd.2012.6.59
15. A. D. Brjuno, Analytic form of differential equations I, Trudy. Moskov. Mat. Obsc., 25 (1971), 119-262.
16. A. D. Brjuno, Analytic form of differential equations II, Trudy. Moskov. Mat. Obsc., 26 (1972), 199-239.
17. H. L. Her, J. G. You, Full measure reducibility for a generic one-parameter family of quasi-periodic linear systems, J. Dyn. Differ. Equ., 20 (2008), 831. https://doi.org/10.1007/s10884-008-9113-6
18. P. Lancaster, Theory of matrices, New York and London: Academic Press, 1969.
19. J. G. You, Perturbations of lower dimensional tori for Hamiltonian systems, J. Differ. Equ., 152 (1999), 1-29. https://doi.org/10.1006/jdeq.1998.3515
20. M. Afzal, S. Z. Guo, D. X. Piao, On the reducibility of a class of linear almost periodic Hamiltonian systems, Qual. Theory Dyn. Syst., 18 (2019), 723-738. https://doi.org/10.1007/s12346-018-03099
21. F. Rellich, Perturbation theory of eigenvalue problem, New York: Gordon and Breach, 1969.
22. J. G. You, Perturbations of lower dimensional tori for Hamiltonian systems, J. Differ. Equ., 152 (1999), 1-29. https://doi.org/10.1006/jdeq.1998.3515

AIMS Press
© 2022 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/4.0)

